

# First-Order Model-Checking

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The Parameterized Complexity Summer School

Vienna, 03.09.2017

# Model-checking

## The model-checking problem

Let  $\mathcal{L}$  be a logic and let  $\mathcal{C}$  be a class of structures.

$\text{MC}(\mathcal{L}, \mathcal{C})$

*Input:* Structure  $\mathfrak{A} \in \mathcal{C}$ , formula  $\varphi \in \mathcal{L}$

*Problem:* Does  $\mathfrak{A}$  satisfy  $\varphi$ , in symbols,  $\mathfrak{A} \models \varphi$ ?

## First-order logic FO

- Subgraph isomorphism for pattern graph  $H$  (on vertex set  $\{1, \dots, n\}$ ):

$$\exists x_1 \dots \exists x_n \left( \bigwedge_{ij \in E(H)} E(x_i, x_j) \wedge \bigwedge_{ij \notin E(H)} \neg E(x_i, x_j) \right)$$

- Dominating set of size at most  $k$ :

$$\exists x_1 \dots \exists x_k \forall y \left( \bigvee_{1 \leq i \leq k} (y = x_i \vee E(y, x_i)) \right)$$

# Algorithmic meta-theorems

- Many computational problems can be described elegantly in logics.

## Algorithmic meta-theorem

Every problem definable in a given logic  $\mathcal{L}$  is tractable.

- Provide uniform explanation why problems are tractable.
- Establish general algorithmic techniques for solving them.
- Corresponding intractability results for logics exhibit natural boundaries beyond which these techniques fail.

# Complexity of first-order model-checking

- $\Sigma_0 = \Pi_0$ : quantifier-free first-order formulas.
- For  $t \geq 0$ , let  $\Sigma_{t+1}$  be the set of all formulas

$$\exists x_1 \dots \exists x_k \varphi, \quad \text{where } \varphi \in \Pi_t.$$

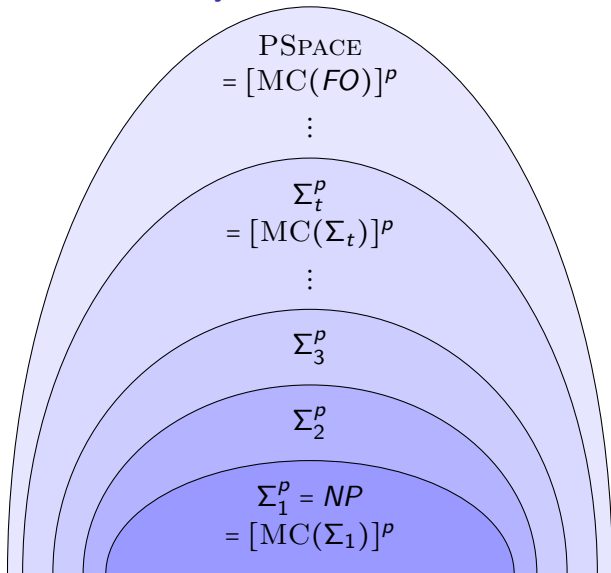
- For  $t \geq 0$ , let  $\Pi_{t+1}$  be the set of all formulas

$$\forall x_1 \dots \forall x_k \varphi, \quad \text{where } \varphi \in \Sigma_t.$$

## Example

- $\exists x_1 \dots \exists x_n \left( \bigwedge_{ij \in E(H)} E(x_i, x_j) \wedge \bigwedge_{ij \notin E(H)} \neg E(x_i, x_j) \right) \in \Sigma_1.$
- $\exists x_1 \dots \exists x_k \forall y \left( \bigvee_{1 \leq i \leq k} (y = x_i \vee E(y, x_i)) \right) \in \Sigma_2.$

# Complexity of first-order model-checking – the polynomial hierarchy



# Parameterized model-checking

## The parameterized model-checking problem

Let  $\mathcal{L}$  be a logic and let  $\mathcal{C}$  be a class of structures.

$MC(\mathcal{L}, \mathcal{C})$

*Input:* Structure  $\mathfrak{A} \in \mathcal{C}$ , formula  $\varphi \in \mathcal{L}$

*Parameter:*  $|\varphi|$

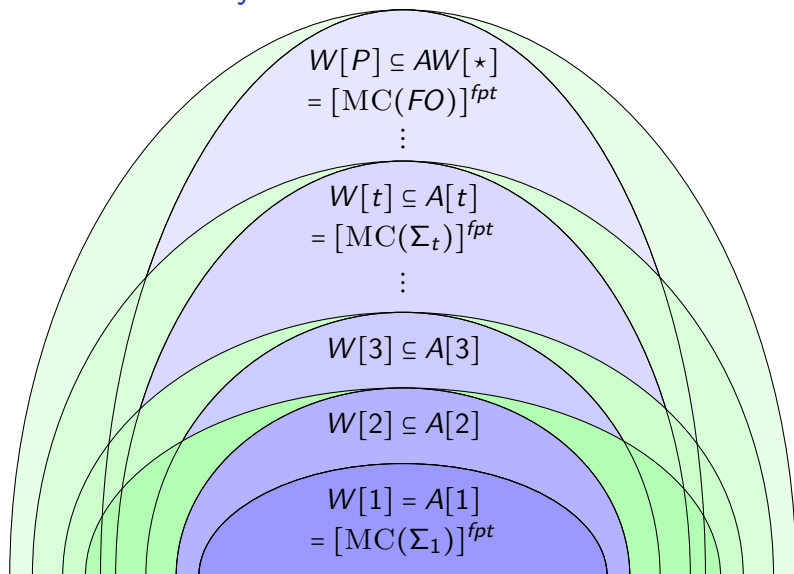
*Problem:* Does  $\mathfrak{A}$  satisfy  $\varphi$ , in symbols,  $\mathfrak{A} \models \varphi$ ?

- For  $t \geq 1$  let  $\Sigma_{t,1}$  be the set of all  $\Sigma_t$  formulas such that all quantifier blocks after the leading existential block have length  $\leq 1$ .

## Example

- $\exists x_1 \dots \exists x_n \left( \bigwedge_{ij \in E(H)} E(x_i, x_j) \wedge \bigwedge_{ij \notin E(H)} \neg E(x_i, x_j) \right) \in \Sigma_{1,1} = \Sigma_1$ .
- $\exists x_1 \dots \exists x_k \forall y \left( \bigvee_{1 \leq i \leq k} (y = x_i \vee E(y, x_i)) \right) \in \Sigma_{2,1}$ .

# Parameterized complexity of first-order model-checking – $W$ - and $A$ -hierarchy



# Parameterized complexity of first-order model-checking

DOMINATING SET is  $W[2]$ -hard.

DOMINATING SET

*Input:* Graph  $G$  and  $k \in \mathbb{N}$

*Parameter:*  $k$

*Problem:* Do there exist  $k$  vertices which dominate  $G$ ?

CLIQUE-DOMINATING SET is  $A[2]$ -hard.

CLIQUE-DOMINATING SET

*Input:* Graph  $G$  and  $k, \ell \in \mathbb{N}$

*Parameter:*  $k + \ell$

*Problem:* Do there exist  $k$  vertices which dominate every clique of size  $\ell$ ?



# Algorithmic meta-theorems

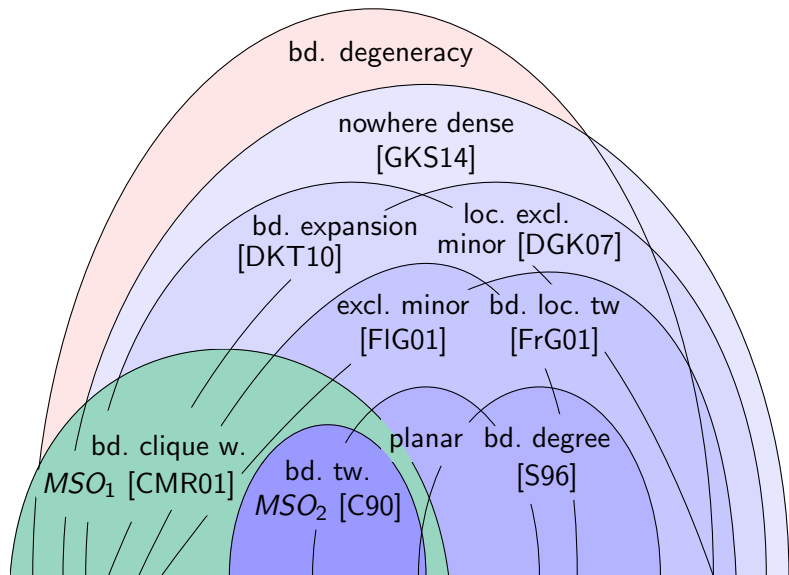
- Many computational problems can be described elegantly in logics.

## Algorithmic meta-theorem

Every problem definable in a given logic  $\mathcal{L}$  is tractable **on every class of structures satisfying a certain property.**

- Provide a uniform explanation why natural classes of problems are tractable **on a certain class of structures (which may be sufficient for practical applications).**
- Establish general algorithmic techniques for solving them.
- Corresponding intractability results for logics exhibit natural boundaries beyond which these techniques fail.

# Sparse graph classes with fpt model-checking



# Sparse graph classes with fpt model-checking

## Theorem [Grohe, Kreutzer, S. 14]

If  $\mathcal{C}$  is nowhere dense, then  $\text{MC}(FO)$  can be solved in time  $f(|\varphi|) \cdot n^{1+\varepsilon}$  on every  $n$ -vertex graph  $G \in \mathcal{C}$ .

## Theorem [Kreutzer 09], [Dvořák, Král', Thomas 11]

If  $\mathcal{C}$  is somewhere dense and closed under taking subgraphs, then  $\text{MC}(FO)$  on  $\mathcal{C}$  is  $AW[\star]$ -complete.

## Corollary (assuming $\text{FPT} \neq AW[\star]$ )

If  $\mathcal{C}$  is closed under taking subgraphs, then  $\text{MC}(FO)$  on  $\mathcal{C}$  is fpt if and only if  $\mathcal{C}$  is nowhere dense.

# Methods for sparse graphs

## Theorem [Grohe, Kreutzer, S., 14]

If  $\mathcal{C}$  is nowhere dense, then  $\text{MC}(\text{FO})$  can be solved in time  $f(|\varphi|) \cdot n^{1+\varepsilon}$  on every  $n$ -vertex graph  $G \in \mathcal{C}$ .

## Methods

- Gaifman's theorem:  $\varphi(x)$  equivalent to Boolean combination of local formulas and basic local formulas

$$\exists x_1 \dots \exists x_k \bigwedge_{i \neq j} \text{dist}(x_i, x_j) > 2r \wedge \bigwedge_i \psi^{(r)}(x_i).$$

- Find  $r$ -neighbourhoods in which  $\psi$  is true ( $r$  only depends on  $\varphi$ ).
- Solve distance- $2r$  independent set problem ( $k$  depends only on  $\varphi$ ).
- Evaluate Boolean combination.

# Lower bounds on somewhere dense graphs

## Theorem

Let  $\mathcal{C}$  be somewhere dense and closed under taking subgraphs. Then there exists  $p \in \mathbb{N}$  such that for every graph  $H$  we have  $H^p \in \mathcal{C}$ , where  $H^p$  is the  $p$ -subdivision of  $H$ .

## Proposition

Model checking on  $H^p$  is just as hard as on  $H$ .

# Model-checking beyond sparse graphs

## Corollary (assuming $FPT \neq AW[*]$ )

If  $\mathcal{C}$  is closed under taking subgraphs, then  $MC(FO)$  on  $\mathcal{C}$  is fpt if and only if  $\mathcal{C}$  is nowhere dense.

## Research program

Find the most general classes (which are not closed under taking subgraphs) which admit fpt model-checking.

- Efficient FO-model checking on specific dense graph classes.
    - Model-checking on certain interval graphs is fpt [Ganian et al. 13].
    - Model-checking on bounded width posets is fpt [Gajarský et al. 15].
- There is no clear candidate for a *most general* dense class with tractable model-checking.

## Model-checking beyond sparse graphs – Interpretations

- Assume  $\mathcal{C}$  is a class with  $\text{MC}(FO, \mathcal{C}) \in \text{FPT}$ .
- For a graph  $G$  let  $\bar{G}$  be its complement and let  $\bar{\mathcal{C}} = \{\bar{G} : G \in \mathcal{C}\}$ .

### Proposition

Model-checking on  $\bar{\mathcal{C}}$  is fpt.

Proof.

- Given  $\bar{G} \in \bar{\mathcal{C}}$  and  $\varphi \in FO$ , let  $\varphi'$  be obtained from  $\varphi$  by replacing each atom  $E(x, y)$  by  $\neg E(x, y)$ .
- Then  $\bar{G} \models \varphi \iff G \models \varphi'$ .
- $G$  and  $\varphi'$  are efficiently computable from  $\bar{G}$  and  $\varphi$ .

# Model-checking beyond sparse graphs – Interpretations

- A *simple interpretation*  $\mathcal{J}_\varphi$  is a formula  $\varphi(x, y)$ .
- For a graph  $G = (V, E)$  define

$$\mathcal{J}_\varphi(G) = (V, \{uv : G \models \varphi(u, v) \vee \varphi(v, u)\}).$$

## Example

On the previous slide we had  $\varphi = \neg E(x, y)$  and  $\mathcal{J}_\varphi(G) = \bar{G}$ .

## Interpretation Lemma

Replace in a formula  $\psi$  every occurrence of  $E(x, y)$  by  $(\varphi(x, y) \vee \varphi(y, x))$  to obtain  $\mathcal{J}_\varphi(\psi)$ . Then for every graph  $G$

$$\mathcal{J}_\varphi(G) \models \psi \iff G \models \mathcal{J}_\varphi(\psi).$$

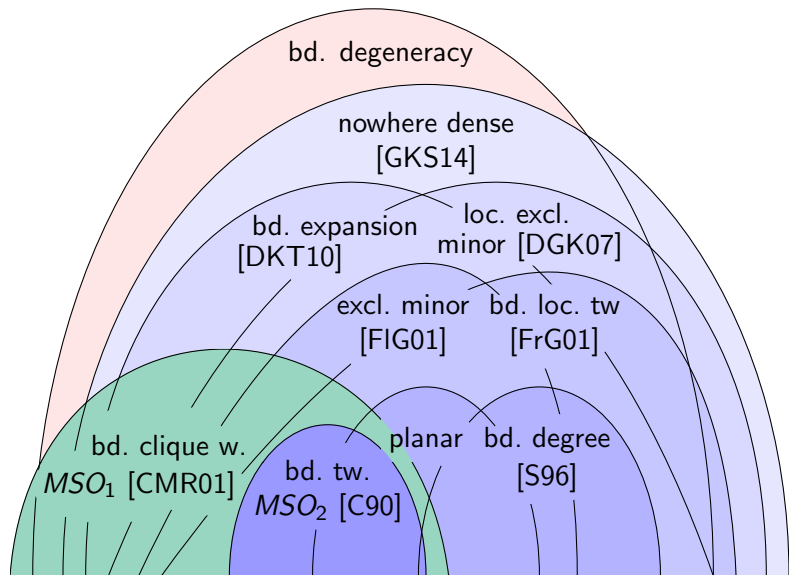


# Model-checking beyond sparse graphs – Interpretations

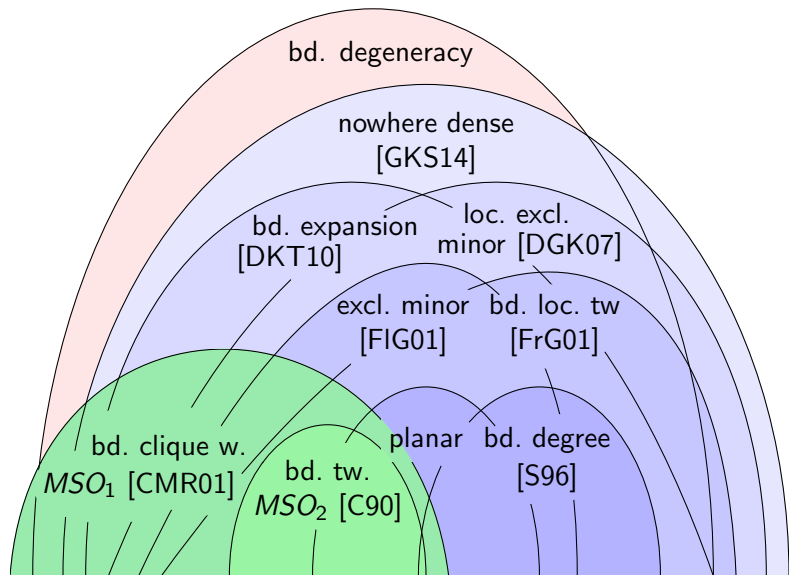
- Let  $\mathcal{C}$  be a class with efficient model-checking.
- Let  $\varphi(x, y)$  be a formula and  $\mathcal{J}_\varphi(\mathcal{C}) = \{\mathcal{J}_\varphi(G) : G \in \mathcal{C}\}$ .
  - On input  $H = \mathcal{J}_\varphi(G) \in \mathcal{J}_\varphi(\mathcal{C})$  and  $\psi$ :
  - Compute  $\mathcal{J}_\varphi(\psi)$ .
  - We have  $H \models \psi \iff G \models \mathcal{J}_\varphi(\psi)$ .
  - $G \models \mathcal{J}_\varphi(\psi)$  can be decided efficiently.

**Problem:** We do not know how to compute  $G$  from  $\mathcal{J}_\varphi(G)$ .

# Sparse graph classes with fpt model-checking



# Sparse graph classes with fpt model-checking

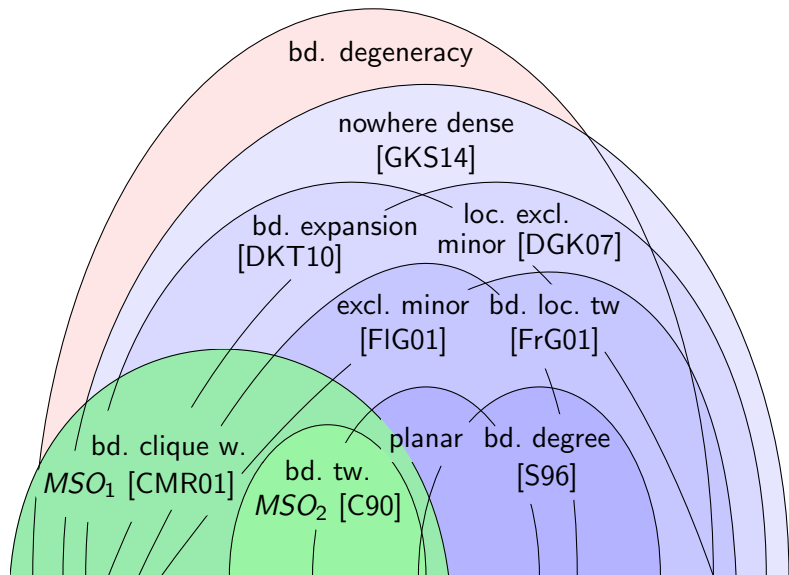


# Model-checking beyond sparse graphs – Interpretations

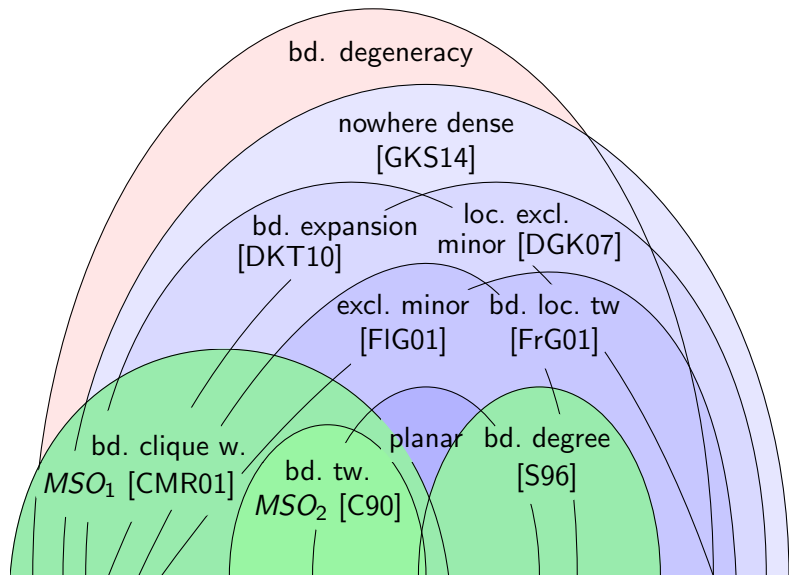
## Theorem

- $\mathcal{C}$  has bounded clique-width  $\iff \mathcal{C}$  is an  $MSO_1$ -interpretation of a class of colored trees.  
 $\implies$  an interpretation of a bounded clique-width graph has again bounded clique-width.
- A clique-decomposition of the input graph can be computed/approximated efficiently.
- $MSO_1/FO$  model-checking on interpretations of bounded clique-width classes is fpt.

# Sparse graph classes with fpt model-checking



# Sparse graph classes with fpt model-checking



# Model-checking beyond sparse graphs – Interpretations

## Definition

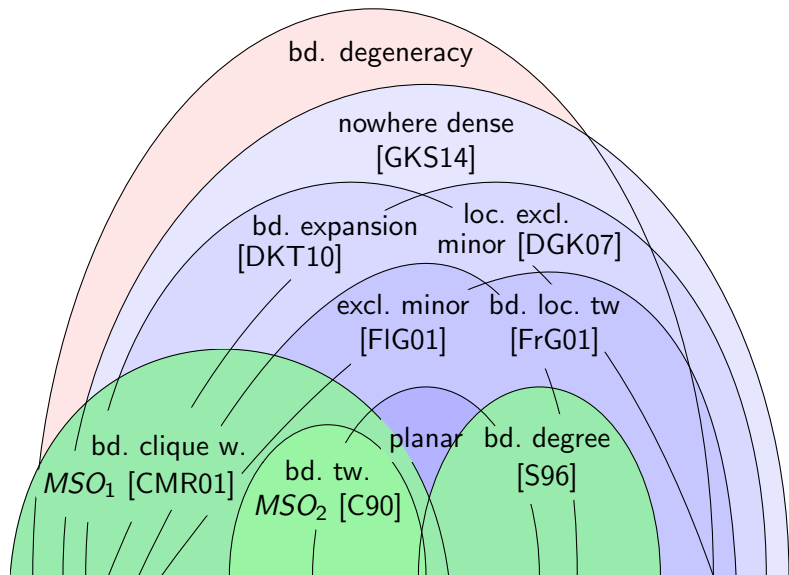
A class  $\mathcal{C}$  of graphs is *near uniform* with parameter  $k$  if it satisfies certain conditions on the *near- $k$ -twin relation* defined by

$$u \sim_k v \iff |N(u) \Delta N(v)| \leq k.$$

## Theorem [Gajarský et al. 16]

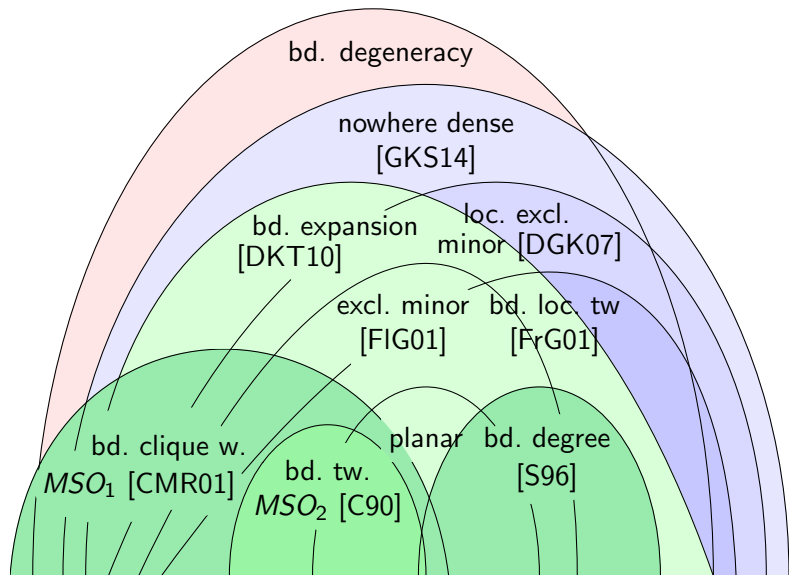
- $\mathcal{C}$  near-uniform  $\iff$   $\mathcal{C}$  interpretation of a bounded degree class.
- A bounded degree pre-image and an interpretation producing the input graph can be computed efficiently from a near uniform input graph.
- Consequently, model-checking on near uniform graphs is fpt.

# Sparse graph classes with fpt model-checking





# Work in progress



# Open problem

## Open problem

- Let  $\mathcal{C}$  be nowhere dense,
- $\varphi(x, y) \in \text{FO}$ , and
- $H = \mathcal{J}_\varphi(G)$ .
- Does there exist for every  $p \in \mathbb{N}$  and every  $\varepsilon > 0$  a coloring of  $V(H)$  with  $g(p, \varepsilon) \cdot n^\varepsilon$  colors such that the subgraph of  $H$  induced by any  $p$  color classes has clique-width/shrub-depth at most  $f(p)$ ?

# Model-checking beyond sparse graphs – Model-theory

## Question

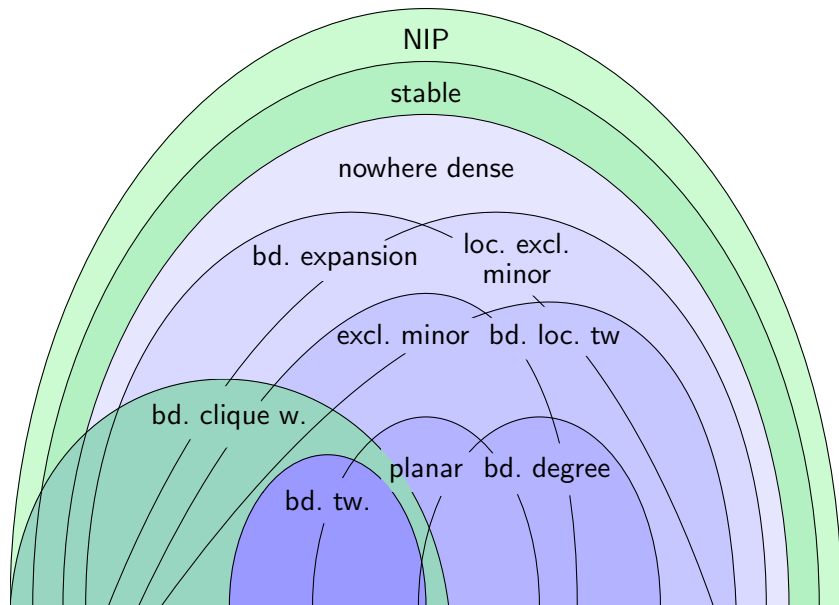
Could tractability of FO on nowhere dense classes be merely an artifact of tractability of FO on a much larger class which happens to coincide with nowhere dense classes if closed under subgraphs?

## Theorem [Adler, Adler 14]

Let  $\mathcal{C}$  be a class of graphs which is closed under taking subgraphs. The following are equivalent.

- $\mathcal{C}$  is nowhere dense.
- $\mathcal{C}$  is stable.
- $\mathcal{C}$  does not have the independence property (is NIP).

# The model-theoretic notions



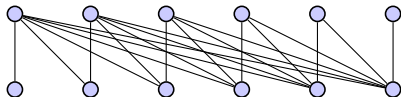
# Stability

## Research program

There is a huge number of combinatorial results which wait to be carried from infinite model theory to the finite.

## Definition

A class  $\mathcal{C}$  of graphs is *stable* if for every first-order formula  $\varphi(\bar{x}, \bar{y})$  there is a constant  $c$  such that the interpretation of  $G \in \mathcal{C}$  by  $\varphi$  excludes a *ladder* of length  $c$  as an induced subgraph.



# Stability and Ramsey-type problems

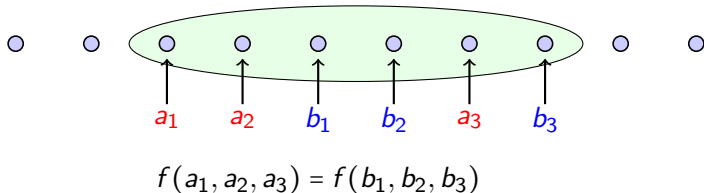
## Definition

Let  $(X, <)$  be a linearly ordered set. Let

$$[(X, <)]^k = \{(x_1, \dots, x_k) \in X^k, x_i < x_j \text{ for } i < j\}.$$

Let  $f : [(X, <)]^k \rightarrow Z$ .

A subordering  $(Y, <)$  is *f-indiscernible* if  $f$  is constant on  $[(Y, <)]^k$ , i.e.,  $f(\bar{a}) = f(\bar{b})$  for all increasing  $k$ -tuples from  $Y$ .



# Stability and Ramsey-type problems

## Example

Let  $G = (V, E)$  be a graph, let  $<$  be an arbitrary order of  $V$  and let

$$f_E : [(V, <)]^2 \rightarrow \{0, 1\} : uv \mapsto \begin{cases} 1 & \text{if } uv \in E(G) \\ 0 & \text{otherwise.} \end{cases} .$$

$(Y, <)$  is  $f_E$ -indiscernible if  $Y$  induces an edgeless graph or a complete graph in  $G$ .

# Stability and Ramsey-type problems

## Finite Ramsey Theorem

For all  $k, m, n \in \mathbb{N}$  there exists  $\ell \in \mathbb{N}$  such that

$$\ell \rightarrow (m)_n^k,$$

i.e., for every  $(X, <)$  of cardinality  $\ell$  and  $f : [(X, <)]^k \rightarrow \{1, \dots, n\}$  there exists a subordering  $(Y, <)$  of cardinality  $m$  which is  $f$ -indiscernible.

## Example (continued)

Number  $\ell$  such that  $\ell \rightarrow (m)_2^2$  (as required for the function  $f_E$ ) satisfies

$$(1 + o(1)) \frac{m}{\sqrt{2e}} 2^{m/2} \leq \ell \leq (1 + o(1)) \frac{4^{m-1}}{\sqrt{\pi m}}.$$



# Stability and Ramsey-type problems

## Definition

Let  $\mathfrak{A}$  be a structure with universe  $A$ ,  $<$  a linear order on  $A$  and let  $\Phi$  be a set of formulas. A subordering  $(Y, <)$  of  $(A, <)$  is  $\Phi$ -*indiscernible* if for every  $\varphi(x_1, \dots, x_k) \in \Phi$  and every pair  $\bar{a}, \bar{b} \in [(A, <)]^k$  we have

$$\mathfrak{A} \models \varphi(\bar{a}) \iff \mathfrak{A} \models \varphi(\bar{b}).$$

We write

$$\ell \rightarrow (m)_\Phi,$$

if for every  $(X, <)$  of cardinality  $\ell$  there exists a subordering  $(Y, <)$  of cardinality  $m$  which is  $\Phi$ -indiscernible.

## Theorem

If  $\mathcal{C}$  is stable, then for all finite  $\Phi \subseteq \text{FO}$  there exists  $t \in \mathbb{N}$  such that  $\ell$  with  $\ell \rightarrow (m)_\Phi$  satisfies  $\ell \leq m^t$ .

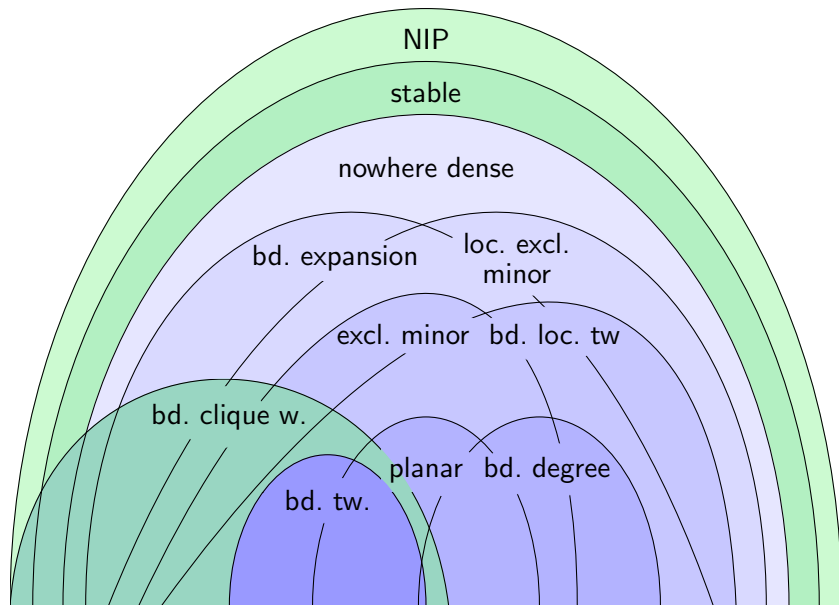
## Algorithmic results based on stability

- We have not been able to apply these facts algorithmically on stable graphs, however,
- we have results for nowhere dense and  $K_{i,j}$ -free graph classes using stability related methods:

### Exemplaric results

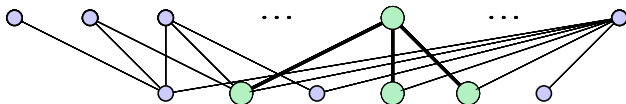
- Let  $\mathcal{C}$  be nowhere dense. Then for every  $r \in \mathbb{N}$  the distance- $r$  dominating set problem admits a polynomial kernel on  $\mathcal{C}$  [Kreutzer, Rabinovich, S. 16] and in fact an almost linear kernel [Eickmeyer et al. 17].
- Let  $\mathcal{C} = \{G : K_{i,j} \notin G\}$ . Then the dominating set problem is fixed-parameter tractable on  $\mathcal{C}$  (a super simple proof for a result of Philip et al. 12).

# The model-theoretic notions



## Definition

A class  $\mathcal{C}$  of graphs is *NIP* if for every first-order formula  $\varphi(\bar{x}, \bar{y})$  there is a constant  $c$  such that the interpretation of  $G \in \mathcal{C}$  by  $\varphi$  has VC-dimension bounded by  $c$ .

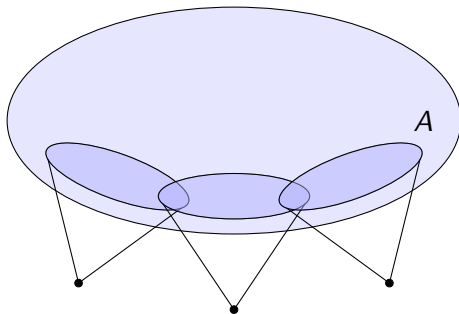


# Methods for graphs of bounded VC-dimension

## Sauer-Shelah Lemma (for graphs)

If  $G$  has VC-dimension  $c$ , then for all  $A \subseteq V(G)$

$$|\{N(v) \cap A : v \in V(G)\}| \leq |A|^c.$$



# Conclusion

- Many computational problems can be described elegantly in logics.
- In general, the model-checking problem for first-order logic is intractable.
- We search for the most general graph classes on which it is tractable.
- The classification for sparse (subgraph closed) classes is complete.
- The methods of interpretations is a strong method to generalize model-checking results. How far can we get?
- The notions of stability and NIP may be very useful in this context.
  - Remark: NIP classes are not the limit...