

ETH and SETH lower bounds

Michał Pilipczuk



Institute of Informatics, University of Warsaw, Poland

Parameterized Complexity Summer School

Vienna, September 1st, 2017

- Take the HAMILTONIAN CYCLE problem.

Motivation

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.
 - How much can you improve the constant 1.657?

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.
 - How much can you improve the constant 1.657?
 - Can you do *significantly* better, e.g. $2^{\mathcal{O}(n/\log n)}$ or $2^{\mathcal{O}(\sqrt{n})}$?

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.
 - How much can you improve the constant 1.657?
 - Can you do *significantly* better, e.g. $2^{\mathcal{O}(n/\log n)}$ or $2^{\mathcal{O}(\sqrt{n})}$?
- Assumption $P \neq NP$ seems too weak to answer these questions.

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.
 - How much can you improve the constant 1.657?
 - Can you do *significantly* better, e.g. $2^{\mathcal{O}(n/\log n)}$ or $2^{\mathcal{O}(\sqrt{n})}$?
- Assumption $P \neq NP$ seems too weak to answer these questions.
- **Parameterized complexity:**

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.
 - How much can you improve the constant 1.657?
 - Can you do *significantly* better, e.g. $2^{\mathcal{O}(n/\log n)}$ or $2^{\mathcal{O}(\sqrt{n})}$?
- Assumption $P \neq NP$ seems too weak to answer these questions.
- **Parameterized complexity:**
 - **FPT:** $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$, $\mathcal{O}^*(2^{\mathcal{O}(k)})$, $\mathcal{O}^*(k^{\mathcal{O}(k^2)})$, $\mathcal{O}^*(2^{2^{\mathcal{O}(k)}})$, ...

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.
 - How much can you improve the constant 1.657?
 - Can you do *significantly* better, e.g. $2^{\mathcal{O}(n/\log n)}$ or $2^{\mathcal{O}(\sqrt{n})}$?
- Assumption $P \neq NP$ seems too weak to answer these questions.
- **Parameterized complexity:**
 - **FPT:** $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$, $\mathcal{O}^*(2^{\mathcal{O}(k)})$, $\mathcal{O}^*(k^{\mathcal{O}(k^2)})$, $\mathcal{O}^*(2^{2^{\mathcal{O}(k)}})$, ...
 - **XP:** $n^{\mathcal{O}(\log k)}$, $n^{\mathcal{O}(\sqrt{k})}$, $n^{\mathcal{O}(k)}$, $n^{2^{\mathcal{O}(k)}}$, ...

- Take the HAMILTONIAN CYCLE problem.
- **Algorithms:**
 - Brute-force $\mathcal{O}(n!)$.
 - $\mathcal{O}^*(2^n)$ Held-Karp dynamic programming.
 - Currently fastest: $\mathcal{O}(1.657^n)$ [Björklund, 2010].
- **Lower bounds:**
 - No poly-time algorithm under $P \neq NP$.
 - How much can you improve the constant 1.657?
 - Can you do *significantly* better, e.g. $2^{\mathcal{O}(n/\log n)}$ or $2^{\mathcal{O}(\sqrt{n})}$?
- Assumption $P \neq NP$ seems too weak to answer these questions.
- **Parameterized complexity:**
 - **FPT:** $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$, $\mathcal{O}^*(2^{\mathcal{O}(k)})$, $\mathcal{O}^*(k^{\mathcal{O}(k^2)})$, $\mathcal{O}^*(2^{2^{\mathcal{O}(k)}})$, ...
 - **XP:** $n^{\mathcal{O}(\log k)}$, $n^{\mathcal{O}(\sqrt{k})}$, $n^{\mathcal{O}(k)}$, $n^{2^{\mathcal{O}(k)}}$, ...
- Assumption $FPT \neq W[1]$ seems too weak to separate these.

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.
 - 3CNF: φ is a conjunction of clauses, where each clause is a disjunction of at most 3 literals — variables or their negations.

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3)$$

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.
 - 3CNF: φ is a conjunction of clauses, where each clause is a disjunction of at most 3 literals — variables or their negations.

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3)$$

- **Trivial:** $\mathcal{O}^*(2^n)$

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.
 - 3CNF: φ is a conjunction of clauses, where each clause is a disjunction of at most 3 literals — variables or their negations.

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3)$$

- **Trivial:** $\mathcal{O}^*(2^n)$
- **Smarter:**

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.
 - 3CNF: φ is a conjunction of clauses, where each clause is a disjunction of at most 3 literals — variables or their negations.

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3)$$

- **Trivial:** $\mathcal{O}^*(2^n)$
- **Smarter:**
 - Take any clause not satisfied so far, and branch on the evaluations of the variables: there are at most 7 options for a 3-clause.

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.
 - 3CNF: φ is a conjunction of clauses, where each clause is a disjunction of at most 3 literals — variables or their negations.

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3)$$

- **Trivial:** $\mathcal{O}^*(2^n)$
- **Smarter:**
 - Take any clause not satisfied so far, and branch on the evaluations of the variables: there are at most 7 options for a 3-clause.
 - Hence the running time is $\mathcal{O}^*(7^{n/3}) = \mathcal{O}(1.913^n)$.

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.
 - 3CNF: φ is a conjunction of clauses, where each clause is a disjunction of at most 3 literals — variables or their negations.

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3)$$

- **Trivial:** $\mathcal{O}^*(2^n)$
- **Smarter:**
 - Take any clause not satisfied so far, and branch on the evaluations of the variables: there are at most 7 options for a 3-clause.
 - Hence the running time is $\mathcal{O}^*(7^{n/3}) = \mathcal{O}(1.913^n)$.
- **Currently fastest:** $\mathcal{O}(1.308^n)$ [PPSZ]

3SAT: complexity status

- 3SAT: given formula φ in 3CNF with n variables and m clauses, decide whether φ is satisfiable.
 - 3CNF: φ is a conjunction of clauses, where each clause is a disjunction of at most 3 literals — variables or their negations.

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3)$$

- **Trivial:** $\mathcal{O}^*(2^n)$
- **Smarter:**
 - Take any clause not satisfied so far, and branch on the evaluations of the variables: there are at most 7 options for a 3-clause.
 - Hence the running time is $\mathcal{O}^*(7^{n/3}) = \mathcal{O}(1.913^n)$.
- **Currently fastest:** $\mathcal{O}(1.308^n)$ [PPSZ]
- For every q you can do $(2 - \varepsilon_q)^n$ for q SAT, but $\lim_{q \rightarrow \infty} \varepsilon_q = 0$.

- Questions:

- **Questions:**

- Can you do *significantly* better, that is, obtain running time $2^{o(n)}$?

- **Questions:**

- Can you do *significantly* better, that is, obtain running time $2^{o(n)}$?
- If you do not have a bound on the clause length, can you do anything smarter than brute-force?

- **Questions:**

- Can you do *significantly* better, that is, obtain running time $2^{o(n)}$?
- If you do not have a bound on the clause length, can you do anything smarter than brute-force?

ETH and SETH, first attempt

ETH: 3SAT cannot be solved in time $2^{o(n)}$.

SETH: CNF-SAT cannot be solved in time $\mathcal{O}(\alpha^n)$ for any $\alpha < 2$.

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

Actual statements

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

- These statements are **stronger** than our first attempts.

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

- These statements are **stronger** than our first attempts.
 - Often the weaker statements suffice, but the above are more robust.

Actual statements

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

- These statements are **stronger** than our first attempts.
 - Often the weaker statements suffice, but the above are more robust.
- **Note:** Usually we allow two-sided error algorithms in the definition.

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

- These statements are **stronger** than our first attempts.
 - Often the weaker statements suffice, but the above are more robust.
- **Note:** Usually we allow two-sided error algorithms in the definition.
- **SETH \Rightarrow ETH** (nontrivial)

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

- These statements are **stronger** than our first attempts.
 - Often the weaker statements suffice, but the above are more robust.
- **Note:** Usually we allow two-sided error algorithms in the definition.
- $\text{SETH} \Rightarrow \text{ETH}$ (nontrivial)
- Formulated by Impagliazzo, Paturi, and Zane in 2001.

Actual statements

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

- These statements are **stronger** than our first attempts.
 - Often the weaker statements suffice, but the above are more robust.
- **Note:** Usually we allow two-sided error algorithms in the definition.
- $\text{SETH} \Rightarrow \text{ETH}$ (nontrivial)
- Formulated by Impagliazzo, Paturi, and Zane in 2001.
- Nowadays, standard assumptions for fine-grained complexity theory.

Actual statements

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a $c > 0$ such that 3SAT cannot be solved in $\mathcal{O}(2^{cn})$ time.

Strong Exponential Time Hypothesis, SETH

$$\lim_{q \rightarrow \infty} \delta_q = 1.$$

- These statements are **stronger** than our first attempts.
 - Often the weaker statements suffice, but the above are more robust.
- **Note:** Usually we allow two-sided error algorithms in the definition.
- $\text{SETH} \Rightarrow \text{ETH}$ (nontrivial)
- Formulated by Impagliazzo, Paturi, and Zane in 2001.
- Nowadays, standard assumptions for fine-grained complexity theory.
- **ETH is widely believed, SETH is disputed.**

- We would like to transfer lower bounds via **reductions**.

- We would like to transfer lower bounds via **reductions**.
- A reduction $3\text{SAT} \rightarrow L$ and a too fast algorithm for L would give a too fast algorithm for 3SAT.

- We would like to transfer lower bounds via **reductions**.
- A reduction $3\text{SAT} \rightarrow L$ and a too fast algorithm for L would give a too fast algorithm for 3SAT .

VERTEX COVER

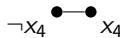
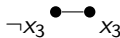
- I:** graph G and $k \in \mathbb{N}$
- Q:** Is there a set $X \subseteq V(G)$ with $|X| \leq k$ such that every edge of G has at least one endpoint in X ?

VERTEX COVER reduction

Let us inspect the standard reduction from 3SAT to VERTEX COVER.



clauses



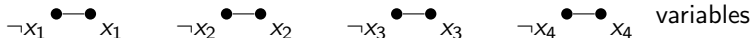
variables

Variable gadgets \rightsquigarrow Edges

Clause gadgets \rightsquigarrow Triangles

VERTEX COVER reduction

Let us inspect the standard reduction from 3SAT to VERTEX COVER.

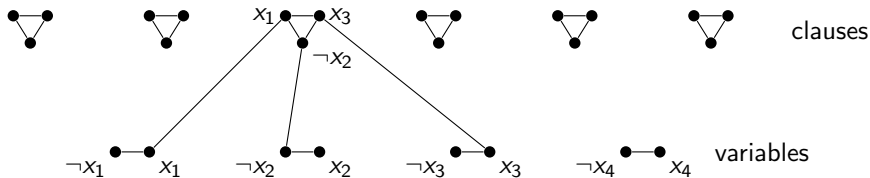


Variable gadgets \rightsquigarrow Edges

Clause gadgets \rightsquigarrow Triangles

VERTEX COVER reduction

Let us inspect the standard reduction from 3SAT to VERTEX COVER.

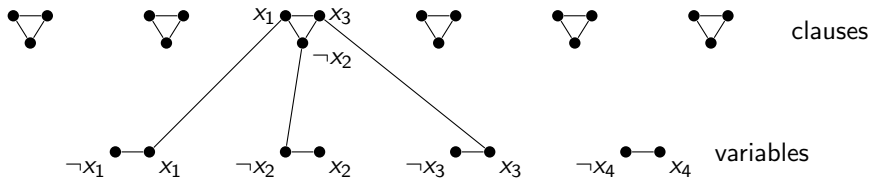


Variable gadgets \rightsquigarrow Edges

Clause gadgets \rightsquigarrow Triangles

VERTEX COVER reduction

Let us inspect the standard reduction from 3SAT to VERTEX COVER.



Variable gadgets \rightsquigarrow Edges

Clause gadgets \rightsquigarrow Triangles

φ is satisfiable iff the created graph has a vertex cover of size $n + 2m$.

VERTEX COVER reduction, analysis

- If $N = 2n + 3m$ is the number of vertices of the output graph, then $N = \mathcal{O}(n + m) = \mathcal{O}(n^3)$.

VERTEX COVER reduction, analysis

- If $N = 2n + 3m$ is the number of vertices of the output graph, then $N = \mathcal{O}(n + m) = \mathcal{O}(n^3)$.
- Hence an $2^{o(N^{1/3})}$ algorithm for VC would give an $2^{o(n)}$ algorithm for 3-SAT, contradicting ETH.

VERTEX COVER reduction, analysis

- If $N = 2n + 3m$ is the number of vertices of the output graph, then $N = \mathcal{O}(n + m) = \mathcal{O}(n^3)$.
- Hence an $2^{o(N^{1/3})}$ algorithm for VC would give an $2^{o(n)}$ algorithm for 3-SAT, contradicting ETH.
- **Gap:** between upper bound $2^{\mathcal{O}(N)}$ and $2^{o(N^{1/3})}$.

VERTEX COVER reduction, analysis

- If $N = 2n + 3m$ is the number of vertices of the output graph, then $N = \mathcal{O}(n + m) = \mathcal{O}(n^3)$.
- Hence an $2^{o(N^{1/3})}$ algorithm for VC would give an $2^{o(n)}$ algorithm for 3-SAT, contradicting ETH.
- **Gap:** between upper bound $2^{\mathcal{O}(N)}$ and $2^{o(N^{1/3})}$.
- If we started with an instance of 3-SAT that was **sparse**, that is, $m = \mathcal{O}(n)$, then a $2^{o(N)}$ lower bound would follow.

Sparsification Lemma

Sparsification Lemma informally

For every constant q , there is a subexponential-time algorithm which reduces the number of clauses of a q CNF formula to $\mathcal{O}(n)$.

Sparsification Lemma

Sparsification Lemma informally

For every constant q , there is a subexponential-time algorithm which reduces the number of clauses of a q CNF formula to $\mathcal{O}(n)$.

Sparsification Lemma

[IPZ, 2001]

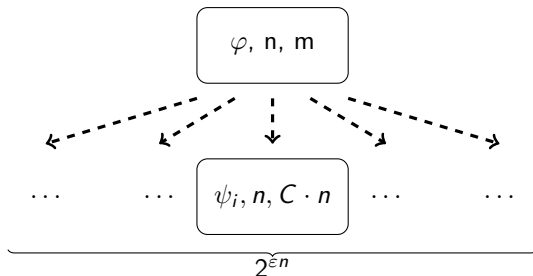
For any $q \geq 3$ and $\varepsilon > 0$, there is a constant $C = C(q, \varepsilon)$ such that any q CNF formula φ can be expressed as $\varphi = \bigvee_{i=1}^t \psi_i$, where $t \leq 2^{\varepsilon n}$ and each ψ_i is a q CNF formula with the same set of variables and at most $C \cdot n$ clauses. Such disjunction can be computed in time $\mathcal{O}^*(2^{\varepsilon n})$.

Sparsification Lemma

Sparsification Lemma

[IPZ, 2001]

For any $q \geq 3$ and $\varepsilon > 0$, there is a constant $C = C(q, \varepsilon)$ such that any q CNF formula φ can be expressed as $\varphi = \bigvee_{i=1}^t \psi_i$, where $t \leq 2^{\varepsilon n}$ and each ψ_i is a q CNF formula with the same set of variables and at most $C \cdot n$ clauses. Such disjunction can be computed in time $\mathcal{O}^*(2^{\varepsilon n})$.



Sparsification Lemma: corollary

Theorem

Unless ETH fails, there is a constant $c > 0$, such that no algorithm solves 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Sparsification Lemma: corollary

Theorem

Unless ETH fails, there is a constant $c > 0$, such that no algorithm solves 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Proof by contradiction:

- Suppose that for every $c > 0$ there is an algorithm \mathcal{A}_c solving 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Sparsification Lemma: corollary

Theorem

Unless ETH fails, there is a constant $c > 0$, such that no algorithm solves 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Proof by contradiction:

- Suppose that for every $c > 0$ there is an algorithm \mathcal{A}_c solving 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.
- Consider any $d > 0$. We want to solve 3SAT in time $\mathcal{O}^*(2^{dn})$.

Sparsification Lemma: corollary

Theorem

Unless ETH fails, there is a constant $c > 0$, such that no algorithm solves 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Proof by contradiction:

- Suppose that for every $c > 0$ there is an algorithm \mathcal{A}_c solving 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.
- Consider any $d > 0$. We want to solve 3SAT in time $\mathcal{O}^*(2^{dn})$.
- Use Sparsification Lemma for $\varepsilon = d/2$. Denote $C = C(3, \varepsilon)$.

Sparsification Lemma: corollary

Theorem

Unless ETH fails, there is a constant $c > 0$, such that no algorithm solves 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Proof by contradiction:

- Suppose that for every $c > 0$ there is an algorithm \mathcal{A}_c solving 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.
- Consider any $d > 0$. We want to solve 3SAT in time $\mathcal{O}^*(2^{dn})$.
- Use Sparsification Lemma for $\varepsilon = d/2$. Denote $C = C(3, \varepsilon)$.
- Solve each ψ_i by $\mathcal{A}_{c'}$, where $c' = \frac{d}{2(C+1)}$.

Sparsification Lemma: corollary

Theorem

Unless ETH fails, there is a constant $c > 0$, such that no algorithm solves 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Proof by contradiction:

- Suppose that for every $c > 0$ there is an algorithm \mathcal{A}_c solving 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.
- Consider any $d > 0$. We want to solve 3SAT in time $\mathcal{O}^*(2^{dn})$.
- Use Sparsification Lemma for $\varepsilon = d/2$. Denote $C = C(3, \varepsilon)$.
- Solve each ψ_i by $\mathcal{A}_{c'}$, where $c' = \frac{d}{2(C+1)}$.
- The total running time is

$$\mathcal{O}^*(2^{\varepsilon n}) + \mathcal{O}^*(2^{\varepsilon n} \cdot 2^{\frac{d}{2(C+1)} \cdot (C+1)n}) = \mathcal{O}^*(2^{dn}).$$

Sparsification Lemma: corollary

Theorem

Unless ETH fails, there is a constant $c > 0$, such that no algorithm solves 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.

Proof by contradiction:

- Suppose that for every $c > 0$ there is an algorithm \mathcal{A}_c solving 3SAT in time $\mathcal{O}^*(2^{c(n+m)})$.
- Consider any $d > 0$. We want to solve 3SAT in time $\mathcal{O}^*(2^{dn})$.
- Use Sparsification Lemma for $\varepsilon = d/2$. Denote $C = C(3, \varepsilon)$.
- Solve each ψ_i by $\mathcal{A}_{c'}$, where $c' = \frac{d}{2(C+1)}$.
- The total running time is

$$\mathcal{O}^*(2^{\varepsilon n}) + \mathcal{O}^*(2^{\varepsilon n} \cdot 2^{\frac{d}{2(C+1)} \cdot (C+1)n}) = \mathcal{O}^*(2^{dn}).$$

Corollary

Under ETH, there is no $2^{o(n+m)}$ -time algorithm for 3SAT, so also no $2^{o(N+M)}$ -time algorithm for VERTEX COVER.

Hardness under ETH via reductions

Suppose there is a reduction from 3SAT to a problem L that produces an instance of size $N \leq f(n + m)$.

Then we can exclude an algorithm for L with running time $2^{o(f^{-1}(N))}$.

Hardness under ETH via reductions

Suppose there is a reduction from 3SAT to a problem L that produces an instance of size $N \leq f(n + m)$.

Then we can exclude an algorithm for L with running time $2^{o(f^{-1}(N))}$.

- The following problems admit **linear** reductions from 3SAT:
 - FEEDBACK VERTEX SET,
 - DOMINATING SET,
 - 3-COLORING,
 - HAMILTONIAN CYCLE, ...

Hardness under ETH via reductions

Suppose there is a reduction from 3SAT to a problem L that produces an instance of size $N \leq f(n + m)$.

Then we can exclude an algorithm for L with running time $2^{o(f^{-1}(N))}$.

- The following problems admit **linear** reductions from 3SAT:
 - FEEDBACK VERTEX SET,
 - DOMINATING SET,
 - 3-COLORING,
 - HAMILTONIAN CYCLE, ...
- Let's see tight bounds for another form of running time.

Planar problems

- Consider PLANAR VERTEX COVER.

Planar problems

- Consider PLANAR VERTEX COVER.
- NP-**hardness**: Take an instance of general VC, and embed it in the plane replacing every crossing with:

Planar problems

- Consider PLANAR VERTEX COVER.
- NP-**hardness**: Take an instance of general VC, and embed it in the plane replacing every crossing with:

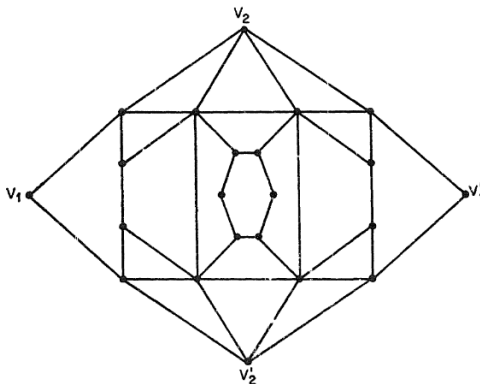


Fig. 11. Crossover H for Theorem 2.7.

- Reduction takes an instance of VC with n vertices and m edges, and outputs an instance with $N = \mathcal{O}((n + m)^2)$ vertices.

- Reduction takes an instance of VC with n vertices and m edges, and outputs an instance with $N = \mathcal{O}((n + m)^2)$ vertices.
- Hence, an $2^{o(\sqrt{N})}$ -time algorithm for PLVC would give an $2^{o(n+m)}$ -time algorithm for VC, contradicting ETH.

- Reduction takes an instance of VC with n vertices and m edges, and outputs an instance with $N = \mathcal{O}((n + m)^2)$ vertices.
- Hence, an $2^{o(\sqrt{N})}$ -time algorithm for PLVC would give an $2^{o(n+m)}$ -time algorithm for VC, contradicting ETH.
- PLVC actually **has** an algorithm working in time $2^{\mathcal{O}(\sqrt{N})}$:

- Reduction takes an instance of VC with n vertices and m edges, and outputs an instance with $N = \mathcal{O}((n + m)^2)$ vertices.
- Hence, an $2^{o(\sqrt{N})}$ -time algorithm for PLVC would give an $2^{o(n+m)}$ -time algorithm for VC, contradicting ETH.
- PLVC actually **has** an algorithm working in time $2^{\mathcal{O}(\sqrt{N})}$:
 - Treewidth DP + planar graph on N vertices has treewidth $\mathcal{O}(\sqrt{N})$.

- Reduction takes an instance of VC with n vertices and m edges, and outputs an instance with $N = \mathcal{O}((n + m)^2)$ vertices.
- Hence, an $2^{o(\sqrt{N})}$ -time algorithm for PLVC would give an $2^{o(n+m)}$ -time algorithm for VC, contradicting ETH.
- PLVC actually **has** an algorithm working in time $2^{\mathcal{O}(\sqrt{N})}$:
 - Treewidth DP + planar graph on N vertices has treewidth $\mathcal{O}(\sqrt{N})$.
- The \sqrt{N} term in the exponent is not a coincidence!

- Consider the CLIQUE problem:

ETH implies $\text{FPT} \neq \text{W}[1]$

- Consider the CLIQUE problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .

- Consider the CLIQUE problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .
 - **Trivial:** $\mathcal{O}^*(n^k)$.

- Consider the CLIQUE problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .
 - **Trivial:** $\mathcal{O}^*(n^k)$.
 - **Fastest known:** $\mathcal{O}^*(n^{\omega k/3}) = \mathcal{O}^*(n^{0.791k})$ [Nešetřil, Poljak]

ETH implies $\text{FPT} \neq \text{W}[1]$

- Consider the CLIQUE problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .
 - **Trivial:** $\mathcal{O}^*(n^k)$.
 - **Fastest known:** $\mathcal{O}^*(n^{\omega k/3}) = \mathcal{O}^*(n^{0.791k})$ [Nešetřil, Poljak]
 - Under $\text{FPT} \neq \text{W}[1]$, no algorithm with running time $f(k) \cdot n^{\mathcal{O}(1)}$.

ETH implies $\text{FPT} \neq \text{W}[1]$

- Consider the CLIQUE problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .
 - **Trivial:** $\mathcal{O}^*(n^k)$.
 - **Fastest known:** $\mathcal{O}^*(n^{\omega k/3}) = \mathcal{O}^*(n^{0.791k})$ [Nešetřil, Poljak]
 - Under $\text{FPT} \neq \text{W}[1]$, no algorithm with running time $f(k) \cdot n^{\mathcal{O}(1)}$.
- We now prove the following:

ETH implies $\text{FPT} \neq \text{W}[1]$

- Consider the **CLIQUE** problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .
 - **Trivial:** $\mathcal{O}^*(n^k)$.
 - **Fastest known:** $\mathcal{O}^*(n^{\omega k/3}) = \mathcal{O}^*(n^{0.791k})$ [Nešetřil, Poljak]
 - Under $\text{FPT} \neq \text{W}[1]$, no algorithm with running time $f(k) \cdot n^{\mathcal{O}(1)}$.
- We now prove the following:

ETH hardness of **CLIQUE**

[Chen, Huang, Kanj, Xia]

Unless ETH fails, **CLIQUE** cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

ETH implies $\text{FPT} \neq \text{W}[1]$

- Consider the **CLIQUE** problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .
 - **Trivial:** $\mathcal{O}^*(n^k)$.
 - **Fastest known:** $\mathcal{O}^*(n^{\omega k/3}) = \mathcal{O}^*(n^{0.791k})$ [Nešetřil, Poljak]
 - Under $\text{FPT} \neq \text{W}[1]$, no algorithm with running time $f(k) \cdot n^{\mathcal{O}(1)}$.
- We now prove the following:

ETH hardness of **CLIQUE**

[Chen, Huang, Kanj, Xia]

Unless ETH fails, **CLIQUE** cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

- **Corollary:** $\text{ETH} \Rightarrow \text{FPT} \neq \text{W}[1]$

ETH implies $\text{FPT} \neq \text{W}[1]$

- Consider the **CLIQUE** problem:
 - Given graph G and $k \in \mathbb{N}$, is there a clique on k vertices in G .
 - **Trivial:** $\mathcal{O}^*(n^k)$.
 - **Fastest known:** $\mathcal{O}^*(n^{\omega k/3}) = \mathcal{O}^*(n^{0.791k})$ [Nešetřil, Poljak]
 - Under $\text{FPT} \neq \text{W}[1]$, no algorithm with running time $f(k) \cdot n^{\mathcal{O}(1)}$.
- We now prove the following:

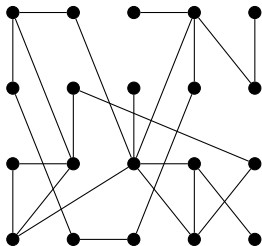
ETH hardness of **CLIQUE**

[Chen, Huang, Kanj, Xia]

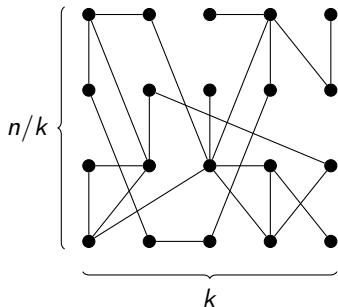
Unless ETH fails, **CLIQUE** cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

- **Corollary:** $\text{ETH} \Rightarrow \text{FPT} \neq \text{W}[1]$
- We start from an instance of **3-COLORING**, for which we already have a $2^{o(n)}$ lower bound.

ETH hardness for CLIQUE

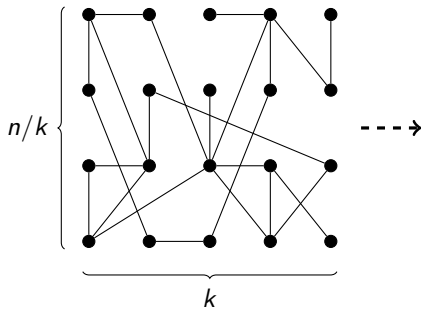


ETH hardness for CLIQUE

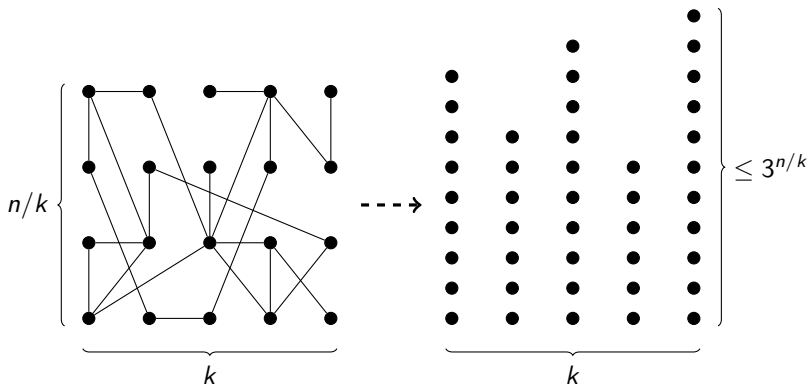


Partition vertices into k groups with n/k vertices each.

ETH hardness for CLIQUE

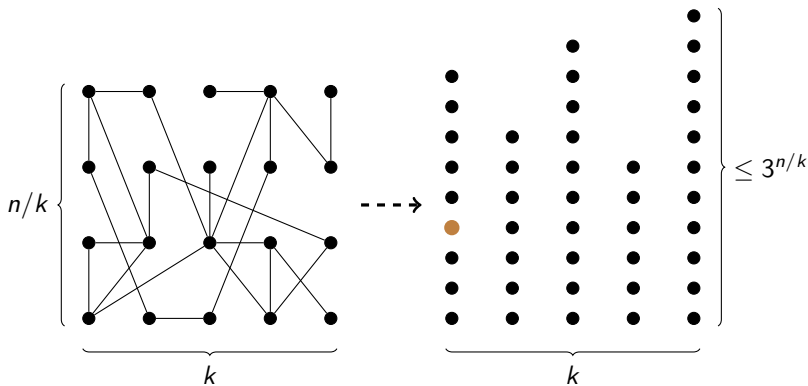


ETH hardness for CLIQUE



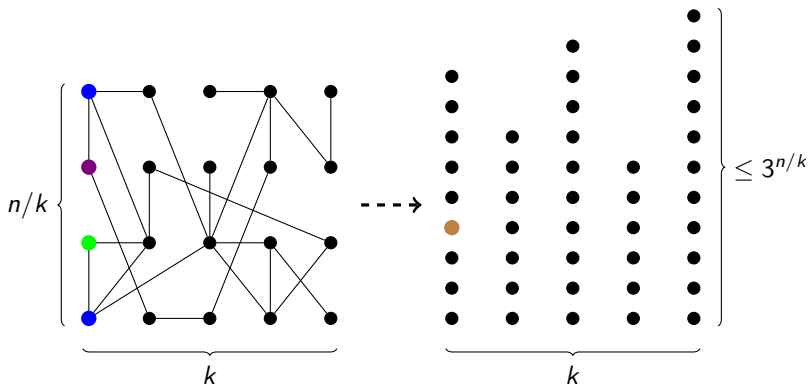
Create one vertex per each **consistent coloring** of each group.

ETH hardness for CLIQUE



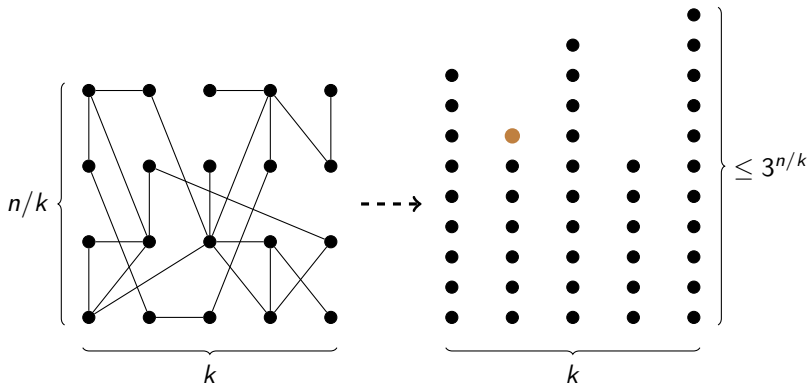
Create one vertex per each **consistent coloring** of each group.

ETH hardness for CLIQUE



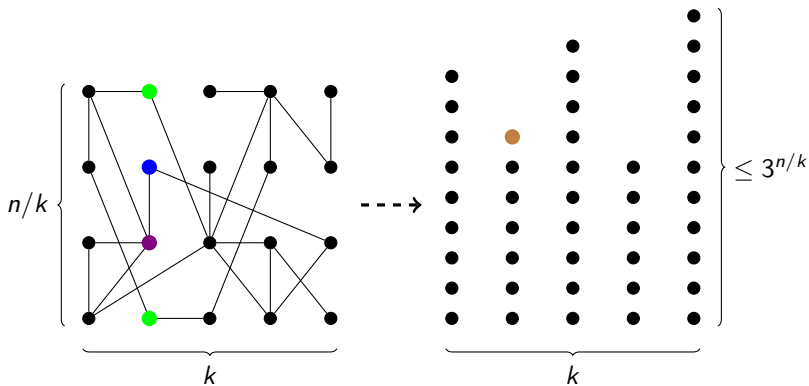
Create one vertex per each **consistent coloring** of each group.

ETH hardness for CLIQUE



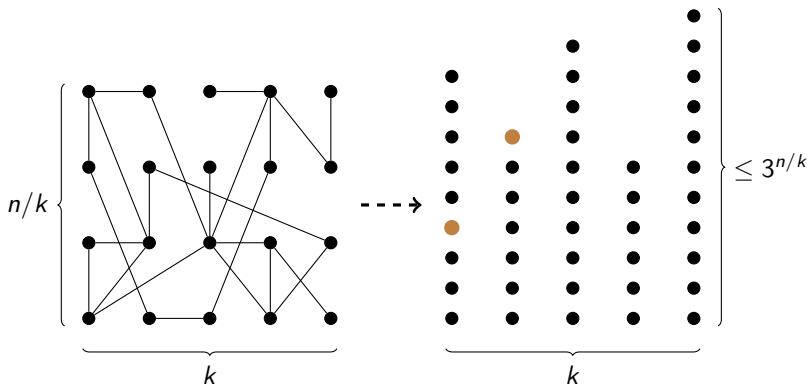
Create one vertex per each **consistent coloring** of each group.

ETH hardness for CLIQUE



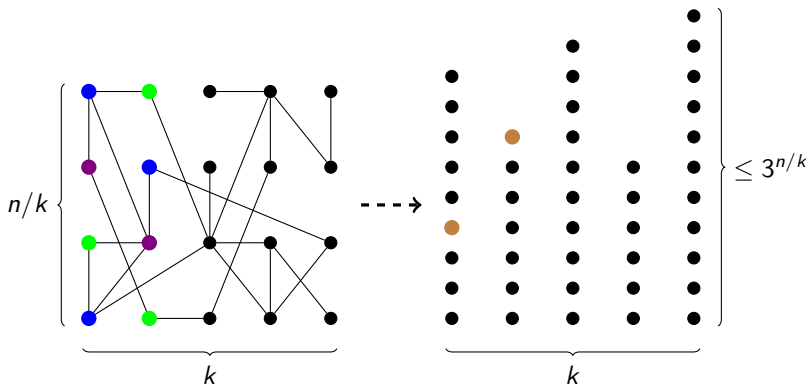
Create one vertex per each **consistent coloring** of each group.

ETH hardness for CLIQUE



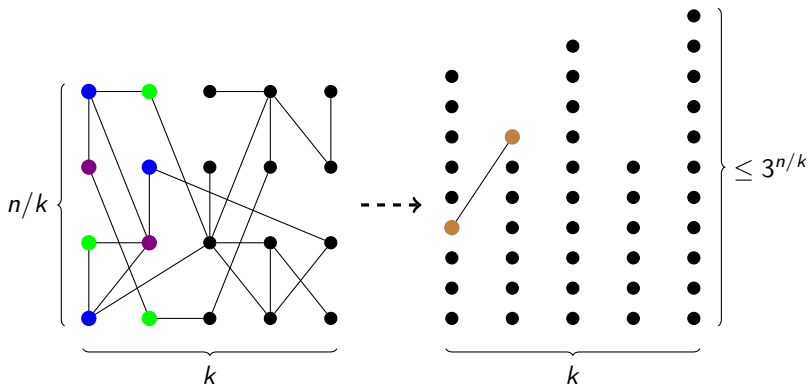
Connect two colorings if they are consistent.

ETH hardness for CLIQUE



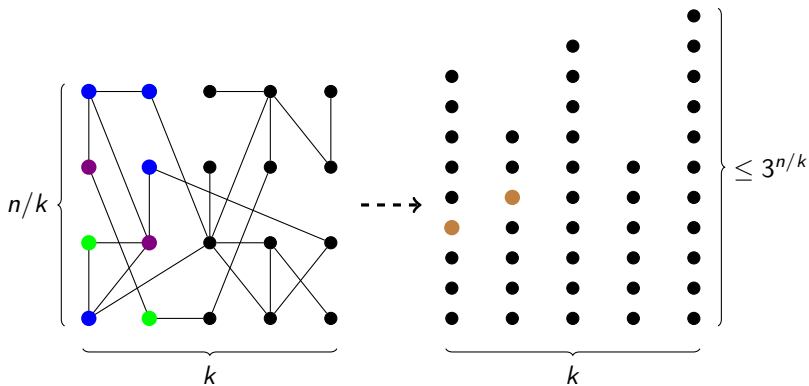
Connect two colorings if they are consistent.

ETH hardness for CLIQUE



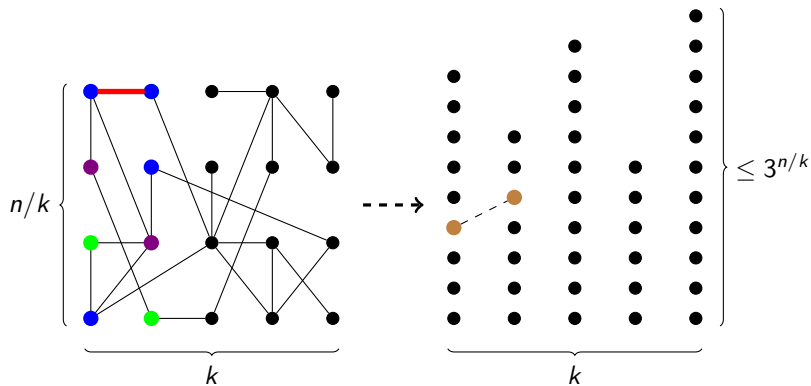
Connect two colorings if they are consistent.

ETH hardness for CLIQUE



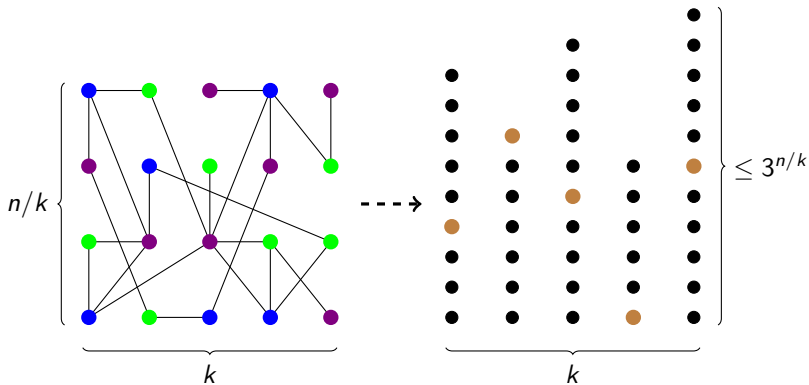
Inconsistent pairs of colorings remain nonadjacent.

ETH hardness for CLIQUE



Inconsistent pairs of colorings remain nonadjacent.

ETH hardness for CLIQUE



A 3-coloring on the left corresponds to a k -clique on the right.

Left graph admits 3-coloring iff right graph contains k -clique.

ETH hardness of CLIQUE

Unless ETH fails, CLIQUE cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

Proof continued:

- The output graph has a k -clique iff the input graph is 3-colorable.

ETH hardness of CLIQUE

Unless ETH fails, CLIQUE cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

Proof continued:

- The output graph has a k -clique iff the input graph is 3-colorable.
- We have introduced $N \leq k \cdot 3^{n/k}$ vertices.

ETH hardness of CLIQUE

Unless ETH fails, CLIQUE cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

Proof continued:

- The output graph has a k -clique iff the input graph is 3-colorable.
- We have introduced $N \leq k \cdot 3^{n/k}$ vertices.
- Let's try $k = \log n$, suppose CLIQUE can be solved in time $2^k \cdot N^{o(k)}$.

ETH hardness of CLIQUE

Unless ETH fails, CLIQUE cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

Proof continued:

- The output graph has a k -clique iff the input graph is 3-colorable.
- We have introduced $N \leq k \cdot 3^{n/k}$ vertices.
- Let's try $k = \log n$, suppose CLIQUE can be solved in time $2^k \cdot N^{o(k)}$.
- $2^k \cdot N^{o(k)} = n \cdot (\log n)^{o(\log n)} \cdot 3^{n \cdot o(\log n) / \log n} = 2^{o(n)}$.

ETH hardness of CLIQUE

Unless ETH fails, CLIQUE cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

Proof continued:

- The output graph has a k -clique iff the input graph is 3-colorable.
- We have introduced $N \leq k \cdot 3^{n/k}$ vertices.
- Let's try $k = \log n$, suppose CLIQUE can be solved in time $2^k \cdot N^{o(k)}$.
- $2^k \cdot N^{o(k)} = n \cdot (\log n)^{o(\log n)} \cdot 3^{n \cdot o(\log n) / \log n} = 2^{o(n)}$.
- Similarly $k = \log \log n$ implies no $2^{2^k} \cdot N^{o(k)}$ time algorithm.

ETH hardness of CLIQUE

Unless ETH fails, CLIQUE cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

Proof continued:

- The output graph has a k -clique iff the input graph is 3-colorable.
- We have introduced $N \leq k \cdot 3^{n/k}$ vertices.
- Let's try $k = \log n$, suppose CLIQUE can be solved in time $2^k \cdot N^{o(k)}$.
- $2^k \cdot N^{o(k)} = n \cdot (\log n)^{o(\log n)} \cdot 3^{n \cdot o(\log n) / \log n} = 2^{o(n)}$.
- Similarly $k = \log \log n$ implies no $2^{2^k} \cdot N^{o(k)}$ time algorithm.
- To exclude all computable $f(k)$, one needs roughly $k = f^{-1}(n)$ (technical difficulties omitted).

ETH hardness of CLIQUE

Unless ETH fails, CLIQUE cannot be solved in time $f(k) \cdot n^{o(k)}$ for any computable function f .

Proof continued:

- The output graph has a k -clique iff the input graph is 3-colorable.
- We have introduced $N \leq k \cdot 3^{n/k}$ vertices.
- Let's try $k = \log n$, suppose CLIQUE can be solved in time $2^k \cdot N^{o(k)}$.
- $2^k \cdot N^{o(k)} = n \cdot (\log n)^{o(\log n)} \cdot 3^{n \cdot o(\log n) / \log n} = 2^{o(n)}$.
- Similarly $k = \log \log n$ implies no $2^{2^k} \cdot N^{o(k)}$ time algorithm.
- To exclude all computable $f(k)$, one needs roughly $k = f^{-1}(n)$ (technical difficulties omitted).
- **Intuition:** We embed the 3^n solution space of 3-COLORING into the N^k solution space of CLIQUE.

- By reductions from `CLIQUE`, one can prove lower bounds on the running times of `XP` algorithms.

- By reductions from **CLIQUE**, one can prove lower bounds on the running times of XP algorithms.
- **Parameter blow-up:** parameter k in a **CLIQUE** instance is transformed into parameter $k' \leq g(k)$ for the output instance.

- By reductions from **CLIQUE**, one can prove lower bounds on the running times of XP algorithms.
- **Parameter blow-up**: parameter k in a **CLIQUE** instance is transformed into parameter $k' \leq g(k)$ for the output instance.
 - Linear blow-up $\rightsquigarrow f(k') \cdot n^{o(k')}$ lower bound

- By reductions from **CLIQUE**, one can prove lower bounds on the running times of XP algorithms.
- **Parameter blow-up**: parameter k in a **CLIQUE** instance is transformed into parameter $k' \leq g(k)$ for the output instance.
 - Linear blow-up $\rightsquigarrow f(k') \cdot n^{o(k')}$ lower bound
 - Quadratic blow-up $\rightsquigarrow f(k') \cdot n^{o(\sqrt{k'})}$ lower bound

- By reductions from **CLIQUE**, one can prove lower bounds on the running times of XP algorithms.
- **Parameter blow-up**: parameter k in a **CLIQUE** instance is transformed into parameter $k' \leq g(k)$ for the output instance.
 - Linear blow-up $\rightsquigarrow f(k') \cdot n^{o(k')}$ lower bound
 - Quadratic blow-up $\rightsquigarrow f(k') \cdot n^{o(\sqrt{k'})}$ lower bound

PLANAR SCATTERED SET

- I:** An edge-weighted planar graph G , $d \in \mathbb{R}^+$, $k \in \mathbb{N}$
- Q:** Are there are k vertices pairwise at distance $\geq d$ from each other?

- By reductions from **CLIQUE**, one can prove lower bounds on the running times of XP algorithms.
- **Parameter blow-up**: parameter k in a **CLIQUE** instance is transformed into parameter $k' \leq g(k)$ for the output instance.
 - Linear blow-up $\rightsquigarrow f(k') \cdot n^{o(k')}$ lower bound
 - Quadratic blow-up $\rightsquigarrow f(k') \cdot n^{o(\sqrt{k'})}$ lower bound

PLANAR SCATTERED SET

- I:** An edge-weighted planar graph G , $d \in \mathbb{R}^+$, $k \in \mathbb{N}$
- Q:** Are there are k vertices pairwise at distance $\geq d$ from each other?

- There is an algorithm with running time $n^{O(\sqrt{k})}$.

- By reductions from **CLIQUE**, one can prove lower bounds on the running times of **XP** algorithms.
- **Parameter blow-up**: parameter k in a **CLIQUE** instance is transformed into parameter $k' \leq g(k)$ for the output instance.
 - Linear blow-up $\rightsquigarrow f(k') \cdot n^{o(k')}$ lower bound
 - Quadratic blow-up $\rightsquigarrow f(k') \cdot n^{o(\sqrt{k'})}$ lower bound

PLANAR SCATTERED SET

- I:** An edge-weighted planar graph G , $d \in \mathbb{R}^+$, $k \in \mathbb{N}$
- Q:** Are there are k vertices pairwise at distance $\geq d$ from each other?

- There is an algorithm with running time $n^{O(\sqrt{k})}$.
- Under **ETH**, there is no algorithm with running time $f(k) \cdot n^{o(\sqrt{k})}$.

- By reductions from **CLIQUE**, one can prove lower bounds on the running times of **XP** algorithms.
- **Parameter blow-up**: parameter k in a **CLIQUE** instance is transformed into parameter $k' \leq g(k)$ for the output instance.
 - Linear blow-up $\rightsquigarrow f(k') \cdot n^{o(k')}$ lower bound
 - Quadratic blow-up $\rightsquigarrow f(k') \cdot n^{o(\sqrt{k'})}$ lower bound

PLANAR SCATTERED SET

- I:** An edge-weighted planar graph G , $d \in \mathbb{R}^+$, $k \in \mathbb{N}$
- Q:** Are there k vertices pairwise at distance $\geq d$ from each other?

- There is an algorithm with running time $n^{\mathcal{O}(\sqrt{k})}$.
- Under **ETH**, there is no algorithm with running time $f(k) \cdot n^{o(\sqrt{k})}$.
 - The reduction transforms an instance of **CLIQUE** with parameter k into an instance of **PLANAR SCATTERED SET** with parameter $\mathcal{O}(k^2)$.

- **Goal:** Tight asymptotic bounds on $f(k)$ in the $f(k) \cdot n^{\mathcal{O}(1)}$ running times for FPT problems.

ETH and parameterized complexity

- **Goal:** Tight asymptotic bounds on $f(k)$ in the $f(k) \cdot n^{\mathcal{O}(1)}$ running times for FPT problems.
 - $\mathcal{O}^*(2^{o(k)})$ algorithm for VC would be also a $2^{o(N)}$ algorithm. ⚡

ETH and parameterized complexity

- **Goal:** Tight asymptotic bounds on $f(k)$ in the $f(k) \cdot n^{\mathcal{O}(1)}$ running times for FPT problems.
 - $\mathcal{O}^*(2^{o(k)})$ algorithm for VC would be also a $2^{o(N)}$ algorithm. ⚡
 - $\mathcal{O}^*(2^{o(\sqrt{k})})$ algorithm for PLVC would be also a $2^{o(\sqrt{N})}$ algorithm. ⚡

- **Goal:** Tight asymptotic bounds on $f(k)$ in the $f(k) \cdot n^{\mathcal{O}(1)}$ running times for FPT problems.
 - $\mathcal{O}^*(2^{o(k)})$ algorithm for VC would be also a $2^{o(N)}$ algorithm. ⚡
 - $\mathcal{O}^*(2^{o(\sqrt{k})})$ algorithm for PLVC would be also a $2^{o(\sqrt{N})}$ algorithm. ⚡
 - These are tight, as there are $\mathcal{O}^*(2^k)$ and $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ time algorithms, respectively.

ETH and parameterized complexity

- **Goal:** Tight asymptotic bounds on $f(k)$ in the $f(k) \cdot n^{\mathcal{O}(1)}$ running times for FPT problems.
 - $\mathcal{O}^*(2^{o(k)})$ algorithm for VC would be also a $2^{o(N)}$ algorithm. ⚡
 - $\mathcal{O}^*(2^{o(\sqrt{k})})$ algorithm for PLVC would be also a $2^{o(\sqrt{N})}$ algorithm. ⚡
 - These are tight, as there are $\mathcal{O}^*(2^k)$ and $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ time algorithms, respectively.
- **Note:** For the reduction from 3SAT to, say, VC, it would be sufficient to have the **parameter** bounded linearly in $n + m$, while the output instance size may be polynomial.

ETH and parameterized complexity

- **Goal:** Tight asymptotic bounds on $f(k)$ in the $f(k) \cdot n^{\mathcal{O}(1)}$ running times for FPT problems.
 - $\mathcal{O}^*(2^{\mathcal{O}(k)})$ algorithm for VC would be also a $2^{\mathcal{O}(N)}$ algorithm. ⚡
 - $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ algorithm for PLVC would be also a $2^{\mathcal{O}(\sqrt{N})}$ algorithm. ⚡
 - These are tight, as there are $\mathcal{O}^*(2^k)$ and $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ time algorithms, respectively.
- **Note:** For the reduction from 3SAT to, say, VC, it would be sufficient to have the **parameter** bounded linearly in $n + m$, while the output instance size may be polynomial.
 - If $N = (n + m)^{\mathcal{O}(1)}$ and $k = \mathcal{O}(n + m)$, then $2^{\mathcal{O}(k)} \cdot N^{\mathcal{O}(1)} = 2^{\mathcal{O}(n+m)}$.

ETH and parameterized complexity

- **Goal:** Tight asymptotic bounds on $f(k)$ in the $f(k) \cdot n^{\mathcal{O}(1)}$ running times for FPT problems.
 - $\mathcal{O}^*(2^{o(k)})$ algorithm for VC would be also a $2^{o(N)}$ algorithm. ⚡
 - $\mathcal{O}^*(2^{o(\sqrt{k})})$ algorithm for PLVC would be also a $2^{o(\sqrt{N})}$ algorithm. ⚡
 - These are tight, as there are $\mathcal{O}^*(2^k)$ and $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ time algorithms, respectively.
- **Note:** For the reduction from 3SAT to, say, VC, it would be sufficient to have the **parameter** bounded linearly in $n + m$, while the output instance size may be polynomial.
 - If $N = (n + m)^{\mathcal{O}(1)}$ and $k = \mathcal{O}(n + m)$, then $2^{o(k)} \cdot N^{\mathcal{O}(1)} = 2^{o(n+m)}$.

Lower bounds for parameterized problems under ETH

Suppose L admits a polynomial-time reduction from 3SAT with output parameter $k \leq f(n + m)$.

Then L does not admit an $\mathcal{O}^*(2^{o(f^{-1}(k))})$ time algorithm unless ETH fails.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.
- Tight bounds for more exotic running times, e.g. $\mathcal{O}^*(2^{2^{o(k)}})$ lower bound for EDGE CLIQUE COVER.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.
- Tight bounds for more exotic running times, e.g. $\mathcal{O}^*(2^{2^{o(k)}})$ lower bound for EDGE CLIQUE COVER.
- Let's examine *slightly super-exponential* FPT algorithms.

$$\text{Slightly super-exponential} = \mathcal{O}^*(2^{\mathcal{O}(k \log k)}) = \mathcal{O}^*(k^{\mathcal{O}(k)})$$

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.
- Tight bounds for more exotic running times, e.g. $\mathcal{O}^*(2^{2^{o(k)}})$ lower bound for EDGE CLIQUE COVER.
- Let's examine *slightly super-exponential* FPT algorithms.

$$\text{Slightly super-exponential} = \mathcal{O}^*(2^{\mathcal{O}(k \log k)}) = \mathcal{O}^*(k^{\mathcal{O}(k)})$$

- Appears naturally:

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.
- Tight bounds for more exotic running times, e.g. $\mathcal{O}^*(2^{2^{o(k)}})$ lower bound for EDGE CLIQUE COVER.
- Let's examine *slightly super-exponential* FPT algorithms.

$$\text{Slightly super-exponential} = \mathcal{O}^*(2^{\mathcal{O}(k \log k)}) = \mathcal{O}^*(k^{\mathcal{O}(k)})$$

- Appears naturally:
 - (a) Iterate through $k!$ possibilities.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.
- Tight bounds for more exotic running times, e.g. $\mathcal{O}^*(2^{2^{o(k)}})$ lower bound for EDGE CLIQUE COVER.
- Let's examine *slightly super-exponential* FPT algorithms.

$$\text{Slightly super-exponential} = \mathcal{O}^*(2^{\mathcal{O}(k \log k)}) = \mathcal{O}^*(k^{\mathcal{O}(k)})$$

- Appears naturally:
 - (a) Iterate through $k!$ possibilities.
 - (b) A branching procedure branches $\mathcal{O}(k)$ times, each time choosing one of $\text{poly}(k)$ options.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.
- Tight bounds for more exotic running times, e.g. $\mathcal{O}^*(2^{2^{o(k)}})$ lower bound for EDGE CLIQUE COVER.
- Let's examine *slightly super-exponential* FPT algorithms.

$$\text{Slightly super-exponential} = \mathcal{O}^*(2^{\mathcal{O}(k \log k)}) = \mathcal{O}^*(k^{\mathcal{O}(k)})$$

- Appears naturally:
 - (a) Iterate through $k!$ possibilities.
 - (b) A branching procedure branches $\mathcal{O}(k)$ times, each time choosing one of $\text{poly}(k)$ options.
 - (c) A treewidth DP has partitions of the bag as the states.

ETH and parameterized complexity

- For many parameterized problems the situation is simple:
 - An algorithm with running time $\mathcal{O}^*(2^{\mathcal{O}(k)})$ exists.
 - The existence of a **subexponential parameterized algorithm**, with running time $\mathcal{O}^*(2^{o(k)})$, can be excluded under ETH using known NP-hardness reductions.
 - For planar problems, runtime $\mathcal{O}^*(2^{\mathcal{O}(\sqrt{k})})$ is often tight under ETH.
- Tight bounds for more exotic running times, e.g. $\mathcal{O}^*(2^{2^{o(k)}})$ lower bound for EDGE CLIQUE COVER.
- Let's examine *slightly super-exponential* FPT algorithms.

$$\text{Slightly super-exponential} = \mathcal{O}^*(2^{\mathcal{O}(k \log k)}) = \mathcal{O}^*(k^{\mathcal{O}(k)})$$

- Appears naturally:
 - (a) Iterate through $k!$ possibilities.
 - (b) A branching procedure branches $\mathcal{O}(k)$ times, each time choosing one of $\text{poly}(k)$ options.
 - (c) A treewidth DP has partitions of the bag as the states.
- We focus on (b), since this is the most typical behavior in parameterized algorithms.

$k \times k$ -CLIQUE

- I:** A graph H on vertex set $\{1, \dots, k\} \times \{1, \dots, k\}$
- Q:** Is there a k -clique in H that contains exactly one vertex from each row?

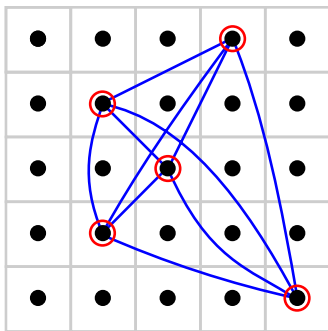
$k \times k$ -CLIQUE

- I:** A graph H on vertex set $\{1, \dots, k\} \times \{1, \dots, k\}$
- Q:** Is there a k -clique in H that contains exactly one vertex from each row?

●	●	●	●	●
●	●	●	●	●
●	●	●	●	●
●	●	●	●	●
●	●	●	●	●

$k \times k$ -CLIQUE

- I:** A graph H on vertex set $\{1, \dots, k\} \times \{1, \dots, k\}$
- Q:** Is there a k -clique in H that contains exactly one vertex from each row?



Lower bound for $k \times k$ -CLIQUE

- **Note:** the input to the problem is of size $\mathcal{O}(k^4)$.

Lower bound for $k \times k$ -CLIQUE

- **Note:** the input to the problem is of size $\mathcal{O}(k^4)$.
- Trivial $\mathcal{O}^*(k^k)$ algorithm: verify all the choices.

Lower bound for $k \times k$ -CLIQUE

- **Note:** the input to the problem is of size $\mathcal{O}(k^4)$.
- Trivial $\mathcal{O}^*(k^k)$ algorithm: verify all the choices.
- **Intuition:** extracts the idea of having k independent 1-in- k choices, similarly as for CLIQUE.

Lower bound for $k \times k$ -CLIQUE

- **Note:** the input to the problem is of size $\mathcal{O}(k^4)$.
- Trivial $\mathcal{O}^*(k^k)$ algorithm: verify all the choices.
- **Intuition:** extracts the idea of having k independent 1-in- k choices, similarly as for CLIQUE.

Hardness for $k \times k$ -CLIQUE

There is a reduction from 3-COLORING to $k \times k$ -CLIQUE that for an input instance with n vertices, outputs an instance with parameter $k = \mathcal{O}(n / \log n)$.

Lower bound for $k \times k$ -CLIQUE

- **Note:** the input to the problem is of size $\mathcal{O}(k^4)$.
- Trivial $\mathcal{O}^*(k^k)$ algorithm: verify all the choices.
- **Intuition:** extracts the idea of having k independent 1-in- k choices, similarly as for CLIQUE.

Hardness for $k \times k$ -CLIQUE

There is a reduction from 3-COLORING to $k \times k$ -CLIQUE that for an input instance with n vertices, outputs an instance with parameter $k = \mathcal{O}(n / \log n)$.

Lower bound for $k \times k$ -CLIQUE

- **Note:** the input to the problem is of size $\mathcal{O}(k^4)$.
- Trivial $\mathcal{O}^*(k^k)$ algorithm: verify all the choices.
- **Intuition:** extracts the idea of having k independent 1-in- k choices, similarly as for CLIQUE.

Hardness for $k \times k$ -CLIQUE

There is a reduction from 3-COLORING to $k \times k$ -CLIQUE that for an input instance with n vertices, outputs an instance with parameter $k = \mathcal{O}(n/\log n)$.

- **Proof sketch:** Apply the reduction for CLIQUE for $k = n/\log n$.

Lower bound for $k \times k$ -CLIQUE

- **Note:** the input to the problem is of size $\mathcal{O}(k^4)$.
- Trivial $\mathcal{O}^*(k^k)$ algorithm: verify all the choices.
- **Intuition:** extracts the idea of having k independent 1-in- k choices, similarly as for CLIQUE.

Hardness for $k \times k$ -CLIQUE

There is a reduction from 3-COLORING to $k \times k$ -CLIQUE that for an input instance with n vertices, outputs an instance with parameter $k = \mathcal{O}(n / \log n)$.

- **Proof sketch:** Apply the reduction for CLIQUE for $k = n / \log n$.

Corollary

Unless ETH fails, there is no algorithm for $k \times k$ -CLIQUE with running time $\mathcal{O}^*(2^{o(k \log k)})$.

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

- **Algorithms** with running time $\mathcal{O}^*(d^{\mathcal{O}(d)})$ and $\mathcal{O}^*(|\Sigma|^{\mathcal{O}(d)})$.

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

- **Algorithms** with running time $\mathcal{O}^*(d^{\mathcal{O}(d)})$ and $\mathcal{O}^*(|\Sigma|^{\mathcal{O}(d)})$.
- **Lower bounds** excluding running time $\mathcal{O}^*(2^{\mathcal{O}(d \log d)})$ or $\mathcal{O}^*(2^{\mathcal{O}(d \log |\Sigma|)})$ under ETH.

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

- **Algorithms** with running time $\mathcal{O}^*(d^{\mathcal{O}(d)})$ and $\mathcal{O}^*(|\Sigma|^{\mathcal{O}(d)})$.
- **Lower bounds** excluding running time $\mathcal{O}^*(2^{o(d \log d)})$ or $\mathcal{O}^*(2^{o(d \log |\Sigma|)})$ under ETH.
- **Further:** treewidth dynamic programming, e.g. CYCLE PACKING:

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

- **Algorithms** with running time $\mathcal{O}^*(d^{\mathcal{O}(d)})$ and $\mathcal{O}^*(|\Sigma|^{\mathcal{O}(d)})$.
- **Lower bounds** excluding running time $\mathcal{O}^*(2^{o(d \log d)})$ or $\mathcal{O}^*(2^{o(d \log |\Sigma|)})$ under ETH.
- **Further:** treewidth dynamic programming, e.g. CYCLE PACKING:
 - Pack the maximum number of vertex-disjoint cycles in a graph.

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

- **Algorithms** with running time $\mathcal{O}^*(d^{\mathcal{O}(d)})$ and $\mathcal{O}^*(|\Sigma|^{\mathcal{O}(d)})$.
- **Lower bounds** excluding running time $\mathcal{O}^*(2^{o(d \log d)})$ or $\mathcal{O}^*(2^{o(d \log |\Sigma|)})$ under ETH.
- **Further:** treewidth dynamic programming, e.g. CYCLE PACKING:
 - Pack the maximum number of vertex-disjoint cycles in a graph.
 - $\mathcal{O}^*(2^{\mathcal{O}(t \log t)})$ -time algorithm by remembering a matching.

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

- **Algorithms** with running time $\mathcal{O}^*(d^{\mathcal{O}(d)})$ and $\mathcal{O}^*(|\Sigma|^{\mathcal{O}(d)})$.
- **Lower bounds** excluding running time $\mathcal{O}^*(2^{o(d \log d)})$ or $\mathcal{O}^*(2^{o(d \log |\Sigma|)})$ under ETH.
- **Further:** treewidth dynamic programming, e.g. CYCLE PACKING:
 - Pack the maximum number of vertex-disjoint cycles in a graph.
 - $\mathcal{O}^*(2^{\mathcal{O}(t \log t)})$ -time algorithm by remembering a matching.
 - Running time $\mathcal{O}^*(2^{o(t \log t)})$ would contradict ETH.

Tight bounds for slightly super-exponential time

- Further reductions give more tightness results for slightly super-exponential time.

CLOSEST STRING

I: Strings $x_1, x_2, \dots, x_n \in \Sigma^L$, $d \in \mathbb{N}$

Q: Is there $y \in \Sigma^L$ that is at Hamming distance $\leq d$ for each x_i ?

- **Algorithms** with running time $\mathcal{O}^*(d^{\mathcal{O}(d)})$ and $\mathcal{O}^*(|\Sigma|^{\mathcal{O}(d)})$.
- **Lower bounds** excluding running time $\mathcal{O}^*(2^{o(d \log d)})$ or $\mathcal{O}^*(2^{o(d \log |\Sigma|)})$ under ETH.
- **Further:** treewidth dynamic programming, e.g. CYCLE PACKING:
 - Pack the maximum number of vertex-disjoint cycles in a graph.
 - $\mathcal{O}^*(2^{\mathcal{O}(t \log t)})$ -time algorithm by remembering a matching.
 - Running time $\mathcal{O}^*(2^{o(t \log t)})$ would contradict ETH.
 - **Note:** For HAMILTONIAN PATH you can get running time $\mathcal{O}^*(4^t)$.

- **Recall:** SETH \Leftrightarrow if $\mathcal{O}(2^{\delta_q n})$ is optimum for q SAT, then $\delta_q \rightarrow 0$.

- **Recall:** SETH \Leftrightarrow if $\mathcal{O}(2^{\delta_q n})$ is optimum for q SAT, then $\delta_q \rightarrow 0$.
- ETH \rightsquigarrow Asymptotics of the exponent

- **Recall:** SETH \Leftrightarrow if $\mathcal{O}(2^{\delta_q n})$ is optimum for q SAT, then $\delta_q \rightarrow 0$.
- ETH \rightsquigarrow Asymptotics of the exponent
- SETH \rightsquigarrow Exact value of the coefficient in the exponent

- **Recall:** $\text{SETH} \Leftrightarrow$ if $\mathcal{O}(2^{\delta_q n})$ is optimum for $q\text{SAT}$, then $\delta_q \rightarrow 0$.
- $\text{ETH} \rightsquigarrow$ Asymptotics of the exponent
- $\text{SETH} \rightsquigarrow$ Exact value of the coefficient in the exponent
- **Reductions for ETH hardness:**
we care only about the **asymptotics** of the parameter blow-up.

- **Recall:** $\text{SETH} \Leftrightarrow$ if $\mathcal{O}(2^{\delta_q n})$ is optimum for $q\text{SAT}$, then $\delta_q \rightarrow 0$.
- $\text{ETH} \rightsquigarrow$ Asymptotics of the exponent
- $\text{SETH} \rightsquigarrow$ Exact value of the coefficient in the exponent
- Reductions for ETH hardness:
we care only about the **asymptotics** of the parameter blow-up.
- Reductions for SETH hardness:
we need to know **precisely** how the parameter is transformed.

- **Recall:** $\text{SETH} \Leftrightarrow$ if $\mathcal{O}(2^{\delta_q n})$ is optimum for $q\text{SAT}$, then $\delta_q \rightarrow 0$.
- $\text{ETH} \rightsquigarrow$ Asymptotics of the exponent
- $\text{SETH} \rightsquigarrow$ Exact value of the coefficient in the exponent
- Reductions for ETH hardness:
we care only about the **asymptotics** of the parameter blow-up.
- Reductions for SETH hardness:
we need to know **precisely** how the parameter is transformed.
- Lower bounds under SETH are more delicate and much scarcer.

- **Recall:** $\text{SETH} \Leftrightarrow$ if $\mathcal{O}(2^{\delta_q n})$ is optimum for $q\text{SAT}$, then $\delta_q \rightarrow 0$.
- $\text{ETH} \rightsquigarrow$ Asymptotics of the exponent
- $\text{SETH} \rightsquigarrow$ Exact value of the coefficient in the exponent
- Reductions for ETH hardness:
we care only about the **asymptotics** of the parameter blow-up.
- Reductions for SETH hardness:
we need to know **precisely** how the parameter is transformed.
- Lower bounds under SETH are more delicate and much scarcer.
 - Also, technically more challenging.

SETH and treewidth DPs

- Many classic problems can be solved in time $\mathcal{O}^*(c^t)$, where c is a constant and t is the width of a given tree decomposition.

SETH and treewidth DPs

- Many classic problems can be solved in time $\mathcal{O}^*(c^t)$, where c is a constant and t is the width of a given tree decomposition.
 - VC and IS in $\mathcal{O}^*(2^t)$, DS and OCT in $\mathcal{O}^*(3^t)$.

SETH and treewidth DPs

- Many classic problems can be solved in time $\mathcal{O}^*(c^t)$, where c is a constant and t is the width of a given tree decomposition.
 - VC and IS in $\mathcal{O}^*(2^t)$, DS and OCT in $\mathcal{O}^*(3^t)$.

Theorem

Assume that CNF-SAT cannot be solved in time $\mathcal{O}^*(c^n)$ for any $c < 2$.
Then for every $\varepsilon > 0$:

- INDEPENDENT SET cannot be solved in time $\mathcal{O}^*((2 - \varepsilon)^p)$;
- DOMINATING SET cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;
- ODD CYCLE TRAVERSAL cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;

where p is the width of a given path decomposition of the input graph.

SETH and treewidth DPs

- Many classic problems can be solved in time $\mathcal{O}^*(c^t)$, where c is a constant and t is the width of a given tree decomposition.
 - VC and IS in $\mathcal{O}^*(2^t)$, DS and OCT in $\mathcal{O}^*(3^t)$.

Theorem

Assume that CNF-SAT cannot be solved in time $\mathcal{O}^*(c^n)$ for any $c < 2$. Then for every $\varepsilon > 0$:

- INDEPENDENT SET cannot be solved in time $\mathcal{O}^*((2 - \varepsilon)^p)$;
- DOMINATING SET cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;
- ODD CYCLE TRAVERSAL cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;

where p is the width of a given path decomposition of the input graph.

Theorem

[Cygan, Kratsch, Nederlof]

HAMILTONIAN PATH can be solved in time $\mathcal{O}^*((2 + \sqrt{2})^p)$, but an algorithm with running time $\mathcal{O}^*((2 + \sqrt{2} - \varepsilon)^p)$ would contradict SETH.

SETH and treewidth DPs

- Many classic problems can be solved in time $\mathcal{O}^*(c^t)$, where c is a constant and t is the width of a given tree decomposition.
 - VC and IS in $\mathcal{O}^*(2^t)$, DS and OCT in $\mathcal{O}^*(3^t)$.

Theorem

Assume that CNF-SAT cannot be solved in time $\mathcal{O}^*(c^n)$ for any $c < 2$. Then for every $\varepsilon > 0$:

- INDEPENDENT SET cannot be solved in time $\mathcal{O}^*((2 - \varepsilon)^p)$;
- DOMINATING SET cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;
- ODD CYCLE TRAVERSAL cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;

where p is the width of a given path decomposition of the input graph.

Theorem

[Cygan, Kratsch, Nederlof]

HAMILTONIAN PATH can be solved in time $\mathcal{O}^*((2 + \sqrt{2})^p)$, but an algorithm with running time $\mathcal{O}^*((2 + \sqrt{2} - \varepsilon)^p)$ would contradict SETH.

SETH and treewidth DPs

- Many classic problems can be solved in time $\mathcal{O}^*(c^t)$, where c is a constant and t is the width of a given tree decomposition.
 - VC and IS in $\mathcal{O}^*(2^t)$, DS and OCT in $\mathcal{O}^*(3^t)$.

Theorem

Assume that CNF-SAT cannot be solved in time $\mathcal{O}^*(c^n)$ for any $c < 2$. Then for every $\varepsilon > 0$:

- INDEPENDENT SET cannot be solved in time $\mathcal{O}^*((2 - \varepsilon)^p)$;
- DOMINATING SET cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;
- ODD CYCLE TRAVERSAL cannot be solved in time $\mathcal{O}^*((3 - \varepsilon)^p)$;

where p is the width of a given path decomposition of the input graph.

Theorem

[Cygan, Kratsch, Nederlof]

HAMILTONIAN PATH can be solved in time $\mathcal{O}^*((2 + \sqrt{2})^p)$, but an algorithm with running time $\mathcal{O}^*((2 + \sqrt{2} - \varepsilon)^p)$ would contradict SETH.

- **Open:** The algorithmic result **does not** work for treewidth.

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

- Denote $n = |U|$ and $m = |\mathcal{F}|$.

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

- Denote $n = |U|$ and $m = |\mathcal{F}|$.
- **Brute-force:** time $\mathcal{O}^*(2^m)$. **DP on subsets:** time $\mathcal{O}^*(2^n)$.

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

- Denote $n = |U|$ and $m = |\mathcal{F}|$.
- **Brute-force:** time $\mathcal{O}^*(2^m)$. **DP on subsets:** time $\mathcal{O}^*(2^n)$.
- Under SETH, no $\mathcal{O}^*(\alpha^m)$ algorithm for SET COVER for any $\alpha < 2$.

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

- Denote $n = |U|$ and $m = |\mathcal{F}|$.
- **Brute-force:** time $\mathcal{O}^*(2^m)$. **DP on subsets:** time $\mathcal{O}^*(2^n)$.
- Under SETH, no $\mathcal{O}^*(\alpha^m)$ algorithm for SET COVER for any $\alpha < 2$.
- Breaking 2 in the base for many covering problems is **equivalent** to breaking it for SET COVER/ n .

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

- Denote $n = |U|$ and $m = |\mathcal{F}|$.
- **Brute-force:** time $\mathcal{O}^*(2^m)$. **DP on subsets:** time $\mathcal{O}^*(2^n)$.
- Under SETH, no $\mathcal{O}^*(\alpha^m)$ algorithm for SET COVER for any $\alpha < 2$.
- Breaking 2 in the base for many covering problems is **equivalent** to breaking it for SET COVER/ n .
 - STEINER TREE, CONN VERTEX COVER, SET PARTITIONING

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

- Denote $n = |U|$ and $m = |\mathcal{F}|$.
- **Brute-force:** time $\mathcal{O}^*(2^m)$. **DP on subsets:** time $\mathcal{O}^*(2^n)$.
- Under SETH, no $\mathcal{O}^*(\alpha^m)$ algorithm for SET COVER for any $\alpha < 2$.
- Breaking 2 in the base for many covering problems is **equivalent** to breaking it for SET COVER/ n .
 - STEINER TREE, CONN VERTEX COVER, SET PARTITIONING
- No known reductions between SET COVER/ n and SET COVER/ m .

SETH and covering problems

SET COVER

I: Universe U , set family $\mathcal{F} \subseteq 2^U$, integer k

Q: Is there a subfamily $\mathcal{G} \subseteq \mathcal{F}$ with $|\mathcal{G}| \leq k$ s.t. $\bigcup \mathcal{G} = U$?

- Denote $n = |U|$ and $m = |\mathcal{F}|$.
- **Brute-force:** time $\mathcal{O}^*(2^m)$. **DP on subsets:** time $\mathcal{O}^*(2^n)$.
- Under SETH, no $\mathcal{O}^*(\alpha^m)$ algorithm for SET COVER for any $\alpha < 2$.
- Breaking 2 in the base for many covering problems is **equivalent** to breaking it for SET COVER/ n .
 - STEINER TREE, CONN VERTEX COVER, SET PARTITIONING
- No known reductions between SET COVER/ n and SET COVER/ m .

Set Cover Conjecture

Let λ_q be the infimum of the set of constants c such that q -SET COVER can be solved in time $\mathcal{O}^*(2^{cn})$, where n is the size of the universe. Then $\lim_{q \rightarrow \infty} \lambda_q = 1$. In particular, there is no algorithm for the general SET COVER problem that runs in $\mathcal{O}^*(\alpha^n)$ for any $\alpha < 2$.

- SETH can be also used to give lower bounds for polynomial-time solvable problems.

- SETH can be also used to give lower bounds for polynomial-time solvable problems.

ORTHOGONAL VECTORS

I: Vectors $v_1, \dots, v_N \in \{0, 1\}^d$

Q: Are there i, j such that $\langle v_i, v_j \rangle = 0$?

- SETH can be also used to give lower bounds for polynomial-time solvable problems.

ORTHOGONAL VECTORS

I: Vectors $v_1, \dots, v_N \in \{0, 1\}^d$

Q: Are there i, j such that $\langle v_i, v_j \rangle = 0$?

Theorem

Unless SETH fails, for every $\delta > 0$ there is $c \in \mathbb{N}$, such that no algorithm for OV with dimension $d = c \log N$ can achieve running time $\mathcal{O}(N^{2-\delta})$.

- SETH can be also used to give lower bounds for polynomial-time solvable problems.

ORTHOGONAL VECTORS

I: Vectors $v_1, \dots, v_N \in \{0, 1\}^d$

Q: Are there i, j such that $\langle v_i, v_j \rangle = 0$?

Theorem

Unless SETH fails, for every $\delta > 0$ there is $c \in \mathbb{N}$, such that no algorithm for OV with dimension $d = c \log N$ can achieve running time $\mathcal{O}(N^{2-\delta})$.

- **Note:** Further hardness results obtained via reductions.

- SETH can be also used to give lower bounds for polynomial-time solvable problems.

ORTHOGONAL VECTORS

- I:** Vectors $v_1, \dots, v_N \in \{0, 1\}^d$
Q: Are there i, j such that $\langle v_i, v_j \rangle = 0$?

Theorem

Unless SETH fails, for every $\delta > 0$ there is $c \in \mathbb{N}$, such that no algorithm for OV with dimension $d = c \log N$ can achieve running time $\mathcal{O}(N^{2-\delta})$.

- **Note:** Further hardness results obtained via reductions.
- **Example:** LONGEST COMMON SUBSEQUENCE in strongly subquadratic time.

- Take input formula φ of q SAT, with n variables and m clauses.

Hardness for OV

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.

Hardness for OV

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.

Hardness for OV

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.

Hardness for OV

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:

Hardness for OV

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .

Hardness for OV

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .
 - **Note:** We create $2^{n/2}$ such vectors.

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .
 - **Note:** We create $2^{n/2}$ such vectors.
- Do the same for V_2 , creating vectors v_η for $\eta: V_2 \rightarrow \{\mathbf{T}, \mathbf{F}\}$.

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .
 - **Note:** We create $2^{n/2}$ such vectors.
- Do the same for V_2 , creating vectors v_η for $\eta: V_2 \rightarrow \{\mathbf{T}, \mathbf{F}\}$.
- **Note:** This takes time $\mathcal{O}^*(2^{n/2})$.

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .
 - **Note:** We create $2^{n/2}$ such vectors.
- Do the same for V_2 , creating vectors v_η for $\eta: V_2 \rightarrow \{\mathbf{T}, \mathbf{F}\}$.
- **Note:** This takes time $\mathcal{O}^*(2^{n/2})$.
- Append 01 to vectors u_η and 10 to vectors v_η .

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .
 - **Note:** We create $2^{n/2}$ such vectors.
- Do the same for V_2 , creating vectors v_η for $\eta: V_2 \rightarrow \{\mathbf{T}, \mathbf{F}\}$.
- **Note:** This takes time $\mathcal{O}^*(2^{n/2})$.
- Append 01 to vectors u_η and 10 to vectors v_η .
- **Claim:** There is a pair of orthogonal vectors iff φ is satisfiable.

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .
 - **Note:** We create $2^{n/2}$ such vectors.
- Do the same for V_2 , creating vectors v_η for $\eta: V_2 \rightarrow \{\mathbf{T}, \mathbf{F}\}$.
- **Note:** This takes time $\mathcal{O}^*(2^{n/2})$.
- Append 01 to vectors u_η and 10 to vectors v_η .
- **Claim:** There is a pair of orthogonal vectors iff φ is satisfiable.
- An algorithm for OV with running time $\mathcal{O}(N^{1.98}) = \mathcal{O}(2^{0.99n})$ would contradict SETH.

- Take input formula φ of q SAT, with n variables and m clauses.
 - **Goal:** decide satisfiability of φ in time $\mathcal{O}(2^{0.99n})$.
 - By Sparsification Lemma, we may assume $m \leq Cn$.
- Partition variables into V_1 and V_2 , each of size $n/2$.
- For every assignment $\eta: V_1 \rightarrow \{\mathbf{T}, \mathbf{F}\}$, create a vector $u_\eta \in \{0, 1\}^m$:
 - At position corresponding to clause c , put 1 iff η **does not** satisfy c .
 - **Note:** We create $2^{n/2}$ such vectors.
- Do the same for V_2 , creating vectors v_η for $\eta: V_2 \rightarrow \{\mathbf{T}, \mathbf{F}\}$.
- **Note:** This takes time $\mathcal{O}^*(2^{n/2})$.
- Append 01 to vectors u_η and 10 to vectors v_η .
- **Claim:** There is a pair of orthogonal vectors iff φ is satisfiable.
- An algorithm for OV with running time $\mathcal{O}(N^{1.98}) = \mathcal{O}(2^{0.99n})$ would contradict SETH.
- **Note:** dimension is $m \leq Cn \leq 2C \log N$.

- Using ETH we can estimate the asymptotics of the exponents.

- Using ETH we can estimate the asymptotics of the exponents.
 - Applies to exponential-time, FPT, XP algorithms, and many more.

Conclusions

- Using ETH we can estimate the asymptotics of the exponents.
 - Applies to exponential-time, FPT, XP algorithms, and many more.
- SETH may give a precise bound on the base of the exponent, but is less plausible and less applicable.

- Using ETH we can estimate the asymptotics of the exponents.
 - Applies to exponential-time, FPT, XP algorithms, and many more.
- SETH may give a precise bound on the base of the exponent, but is less plausible and less applicable.
 - Can be also used to give tight bounds within P .

- Using ETH we can estimate the asymptotics of the exponents.
 - Applies to exponential-time, FPT, XP algorithms, and many more.
- SETH may give a precise bound on the base of the exponent, but is less plausible and less applicable.
 - Can be also used to give tight bounds within **P**.
- **Fine-grained complexity theory**: obtaining matching lower and upper bounds on the complexity of problems of interest.

- Using ETH we can estimate the asymptotics of the exponents.
 - Applies to exponential-time, FPT, XP algorithms, and many more.
- SETH may give a precise bound on the base of the exponent, but is less plausible and less applicable.
 - Can be also used to give tight bounds within \mathbf{P} .
- **Fine-grained complexity theory:** obtaining matching lower and upper bounds on the complexity of problems of interest.
 - **Motivation:** Really tight bounds give us a better understanding of the studied problem, or of its specific parameterization.

- Using ETH we can estimate the asymptotics of the exponents.
 - Applies to exponential-time, FPT, XP algorithms, and many more.
- SETH may give a precise bound on the base of the exponent, but is less plausible and less applicable.
 - Can be also used to give tight bounds within \mathbf{P} .
- **Fine-grained complexity theory:** obtaining matching lower and upper bounds on the complexity of problems of interest.
 - **Motivation:** Really tight bounds give us a better understanding of the studied problem, or of its specific parameterization.
 - Stronger assumptions lead to tighter lower bounds.

- Using ETH we can estimate the asymptotics of the exponents.
 - Applies to exponential-time, FPT, XP algorithms, and many more.
- SETH may give a precise bound on the base of the exponent, but is less plausible and less applicable.
 - Can be also used to give tight bounds within \mathbf{P} .
- **Fine-grained complexity theory:** obtaining matching lower and upper bounds on the complexity of problems of interest.
 - **Motivation:** Really tight bounds give us a better understanding of the studied problem, or of its specific parameterization.
 - Stronger assumptions lead to tighter lower bounds.
- **Thank you for your attention!**